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TECHNICAL REPORT M-70-II

MOBILITY EXERCISE A (MEXA) FIELD TEST PROGRAM

Report 2. -

PERFORMANCE OF MEXA AND THREE MILITARY VEHICLES
IN SOFT SOIL

Volume I

B, G. Schreiner

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Conducted by U. S. Army Engineer Waterways Experiment Station, Vicksburg, Mississippi

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Report 2

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Ьу

B. G. Schreiner



March 1971

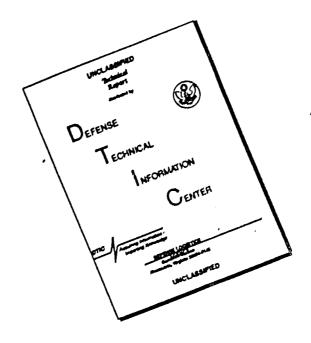
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FOREWORD

The study reported herein was performed by the U. S. Army Engineer Waterways Experiment Station (WES) as a part of the overall Mobility Exercise A (MEXA) program sponsored by the U. S. Army Materiel Command (AMC). Most of the funds for the MEXA program were provided under Project No. 1T062109A131, "Military Evaluation of Geographic Areas"; however, final analysis and report preparation were funded under Project No. 1T062103A046, "Trafficability and Mobility Research," Task O2, "Surface Mobility."

This study was conducted by personnel of the Vehicle Studies Branch under the general supervision of Mr. W. J. Turnbull, Technical Assistant for Soils and Environmental Engineering; Mr. W. G. Shockley, Chief, Mobility and Environmental (M&E) Division; Mr. S. J. Knight, Assistant Chief, M&E Division; Mr. A. A. Rula, Chief, Vehicle Studies Branch, and Mr. E. S. Rush, Chief, Soil-Vehicle Studies Section. Field tests were conducted by personnel of the Soil-Vehicle Studies Section under the direct supervision of Mr. B. G. Schreiner. Messrs. R. P. Smith, C. E. Green, W. E. Willoughby, and S. M. Hodge of the Soil-Vehicle Studies Section contributed to the reduction and analysis of test data. This report and Appendix A were prepared by Mr. Schreiner. Appendix B was written by Miss M. E. Smith and Mr. T. R. Patin of the Mobility Fundamentals Section, Mobility Research Branch, WES. Appendix C was written by Mr. T. F. Czako of the Land Locomotion Division, Mobility Systems Laboratory, U. S. Army Tank-Autometive Command.

This is Report 2 of a series entitled "Mobility Exercise A (MEXA) Field Test Program." The others are as follows: Report 1, "Summary"; Report 3, "Performance of MEXA and Three Military Vehicles in Lateral Obstacles": Report 4, "Performance of MEXA and Three Military Vehicles in

. Vertical Obstacles"; and Report 5, "Performance of MEXA and Three Military Vehicles in Selected Natural Terrains."

Directors of the WES during the conduct of this study and preparation of this report were COL John R. Oswalt, Jr., CE, COL Levi A. Brown, CE, and COL Ernest D. Peixotto, CE. Technical Directors were Messrs. J. B. Tiffany and F. R. Brown.

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CONVERSION FACTORS, BRITISH TO METRIC UNITS OF MEASUREMENT

British units of measurement used in this report can be converted to metric units as follows:

Multiply	Ву	To Obtain
inches feet yards miles (U.S. statute) square inches square miles pounds pounds per square inch pounds per cubic foot miles per hour tons (2000 lb)	2.54 0.3048 0.9144 1.609344 6.4516 2.58999 0.45359237 0.070307 16.0185 1.609344	centimeters meters meters kilometers square centimeters square kilometers kilograms kilograms kilograms per square centimeter kilograms per cubic meter kilometers per hour kilograms

SUMMARY

In the concept phase of Mobility Exercise A (MEXA) the principal purpose was to design vehicles capable of operating in remote areas of the world where extremely soft soils predominate, and to develop a program of tests for evaluating these vehicles in soft soils. As a result of the MEXA concept phase, two 2-1/2-ton wheeled and one 2-1/2-ton tracked vehicles were designed. The designs of the vehicle characteristics were in part derived from three existing systems that provide for predicting vehicle performance relative to soil strength. These systems were the U.S. Army Engineer Waterways Experiment Station (WES) soil trafficability system, the WES mobility numeric system, and the Land Locomotica Laboratory (LLL) soil value system.

After the MEXA vehicles were fabricated, a field test program was designed and conducted. A total of 328 tests were conducted on level clay soils at two sites near Vicksburg, Miss., and at eight sites near Fallon, Nev. The purpose of the test program in soft soil was to evaluate the performance of the three MEXA vehicles (MEXA 10x10, MEXA 8x8, and MEXA track) and three military vehicles (XM+10E1, M35A2 (mod), and M113) on a range of soil strengths. Further purposes of this study were to compare the performances of the three MEXA vehicles with those of the three military vehicles and to compare the measured and predicted performances of the vehicles, using the three prediction systems from which the MEXA vehicles were designed. The measured and predicted performance comparisons are presented in Appendixes A, B, and C of Volume II.

The principal results of the MEXA field test program in soft soil were as follows:

a. Measured (experimental) vehicle cone indexes (VCI's) were established for the six test vehicles. They were:

	Experimental				
Vehicle	vc1 ₅₀	VCI			
XM410E1 M35A? (mod)	32 56	18 27			
M13	29	15			
MEXA 10x10 MEXA 8x8 MEXA track	18 23 21	7 11 7			

Note: VCI50 = VCI for 50 passes. VCI_{lt} = VCI for one pass (tentative).

- The MEXA vehicles were superior to the military vehicles in terms of VCI1t and VCI50.
- b. The best overall one-pass critical-layer criteria determined from field tests for the six vehicles were: the 0- to 6-in. layer was considered to be the normal critical layer unless the rating cone index (RCI) of the 6- to 12-in. layer was less than that of the 0- to 6-in. layer, in which case the 6- to 12-in. layer was considered to be the critical layer.
- c. The soil strength parameter that showed best overall correlation with drawbar pull, motion resistance, speed, and maneuver results was the 0- to 6-in. RCI.
- d. For the soil strengths tested, MEXA vehicle performance in terms of optimum drawbar pull coefficient was superior to that of the military vehicles, thus indicating a greater traction capacity.
- e. Towed motion resistance coefficient was generally less for the MEXA wheeled vehicles than for the military vehicles. On soil below about 40 RCI the MEXA track motion resistance coefficient was lower than that of the military vehicles. Above about 40 RCI the MEXA track motion resistance coefficient was generally greater than that of the M113 and XM410F1, but less than that of the M35A2.
- f. In terms of speed, MEXA vehicles do what they were designed to do, i.e. perform better on soft soils than military vehicles. However, on firm soil and on pavement, speed performance is less than that of the military vehicles. Performance curves indicate that the speeds of the six test vehicles at their respective VCI₁'s appear to be about 2.5 mph.
- g. For the range of soil strengths and specis tested, speed appeared to be a more influential factor than soil strength in affecting the vehicles' ability to make a turn. The minimum soil strength required for maneuvering appears to be the same as VCI_{1t} for the XM410E1, M35A2 (mod), MEXA 8x8, MEXA 10x10, and MEXA track. As for the M113, additional test data are needed to determine the minimum soil strength required for maneuvering.

MOBILITY EXERCISE A (MEXA) FIELD TEST PROGRAM

PERFORMANCE OF MEXA AND THREE MILITARY VEHICLES IN SOFT SOIL

VOLUME I

PART I: INTRODUCTION

Background

- 1. In the initial effort (concept phase) of the Mobility Exercise A (MEXA) program, the principal specific purposes were to design a number of vehicle test beds that could operate in remote areas of the world where extremely soft soils predominate, and to develop a program of tests for evaluating the performance of these vehicles in soft soil. As a result of the MEXA concept phase, two 2-1/2-ton* wheeled and one 2-1/2-ton tracked vehicles were designed.
- 2. The designs of the vehicle characteristics were in part derived from three existing systems that provide for predicting vehicle performance relative to soil strength. The U. S. Army Engineer Waterways Experiment Station (WES) soil trafficability system was used to determine the design characteristics necessary for the vehicles to make 50 successive straight-line passes on a soft soil. The WES mobility numeric system was used to design the characteristics required for the wheeled vehicles to make one pass on a soft soil. The Land Locomotion Laboratory (LLL) soil value system was employed in determining characteristics necessary for both the wheeled and tracked vehicles to make one pass on a soft soil.
- 3. After fabrication of the MEXA vehicles, shakedown tests were conducted in February 1967.² At the same time, a four-phase MEXA field test program was structured.³ The field test program requirements were as follows. Phase I included the determination of the speed performances of the three MEXA vehicles and three military vehicles on soils of strengths

^{*} A table of factors for converting British units of measurement to metric units is presented on page vii.

ranging from so soft as to cause immobilization to and including a hard-surfaced road. Phase II included the establishment of essential soil strength-vehicle performance relations. Phase III included the updating of some of the terrain-vehicle relations required for a cross-country speed prediction model. Phase IV included an evaluation of the accuracy of the updated cross-country speed model in predicting performance from data derived from air-photo interpretation as opposed to data obtained from field measurements. The tests reported herein were conducted under the requirements of Phases I and II.

Purpose

4. The general purpose of this test program was to evaluate the performance of the three MEXA vehicles and the three military vehicles (the XM410E1, the M35A2 (mod), and the M113) on a range of soil strengths. The specific purposes of field tests were to determine (a) the minimum soil strengths, in terms of vehicle cone index (VCI), on which the test vehicles could make one pass and 50 passes, (b) drawbar pull-soil strength relations, (c) towed motion resistance-soil strength relations, (d) maximum speed-soil strength relations, and (e) maneuverability-soil strength relations. It was also the purpose of this strily to compare the performances of the three MEXA vehicles with those of the three military vehicles, and to compare the measured and the predicted performances of the vehicles, using the WES soil trafficability, the WES mobility numeric, and the LLL soil value systems. The latter comparisons are presented in Appendixes Λ, B, and C, respectively, Volume II.

Scope

5. The overall soft soil test program was divided into preliminary and comprehensive test programs. The preliminary program consisted of some of the tests to determine VCI for one pass and 50 passes. This program was conducted from late April to early September 1967 at two sites near Vicksburg, Miss. The comprehensive program included the completion of the VCI

tests and the rest of the tests required to satisfy the purpose of the study. Tests were conducted at eight sites near Fallon, Nev., from early October to early November 1967 and from mid-May to early June 1968. Tests were also conducted at one site near Vicksburg during September 1968. Testing was limited to sites containing clay soil with relatively smooth surfaces. Types of tests, vehicles tested, and number of tests conducted are given in the following tabulation.

	No. of Tests Conducted with Each Venicle							
Type of Test	MEXA 10x10	MEXA 8x8	MEXA Track	XM410E1	M35A2 (mod)	<u>M13</u>	Total	
VCI	18	14	13	12	14	15	86	
Drawbar pull	17	10	14	7	6	9	63	
Towed motion resistance	7	6	7	5	4	5	34	
Speed	8	12	7	5	6	6	44	
Maneuver	20	16	21	20	8	16	101	
Total	70	58	<u>62</u>	49	38	51	328	

Soil measurements and vehicle performance data collected during the field test program were tabulated and analyzed. Analyses of data presented herein included the development of the soil-vehicle relations outlined in the preceding paragraph.

Definitions

6. Certain special terms used in this report are defined below. Soil terms

Unified Soil Classification System (USCS). A soil classification system based on identification of soils according to their textural and plastic qualities and on their grouping with respect to engineering behavior.

<u>Critical layer.</u> The layer of soil that is most pertinent to establishing relations between soil strength and vehicle performance. For 50-pass performance in fine-grained soils and sands with fines, poorly drained,

it is usually the 6- to 12-in. layer; however, it may vary with weight of vehicle and with soil strength profile. For one-pass performance, it is usually some shallower layer.

Soil strength terms

Cone index (CI). An index of the shearing resistance of a medium obtained with a cone penetrometer (shown in fig. 1). The value represents the resistance of the medium to penetration of a 30-deg cone of 0.5-sq-in. base or projected area. The number, although usually considered dimension-



less in trafficability studies, actually denotes pounds of force on the handle divided by the area of the cone base in square inches.

Remolding index (RI). A ratio that expresses the proportion of original strength of a medium that will remain under a moving vehicle. The ratio is determined from cone index measurements made before and after remolding a 6-in.-long sample using the equipment shown in fig. 2. The test sample is obtained with a trafficability sampler (shown in fig. 3).

Rating cone index (RCI). The product of the measured CI and the RI of the same layer.

Shear stress. The greatest shear stress recorded when torque is applied to the sheargraph head during initial soil failure for a particular normal stress maintained on the sheargraph handle. (The sheargraph, shown in fig. 4, is a hand-operated instrument utilizing a coiled spring for measuring torque and load.)

Vehicle terms

Immobilization. The inability of a selfpropelled vehicle to move forward or backward.

 $\underline{\text{Pass.}}$ One trip of the vehicle over a test course.

Fig. 1. Cone penetrometer

Multiple passes. More than one pass of the vehicle in the same path over the test course.

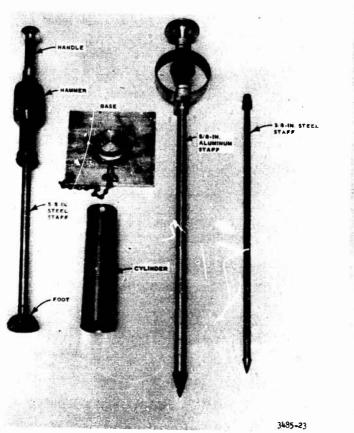


Fig. 2. Remolding equipment

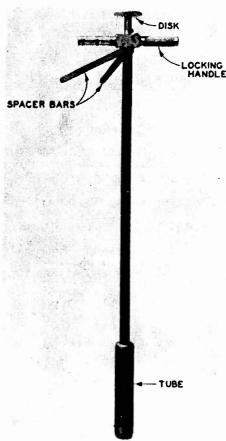


Fig. 3. Trafficability sampler

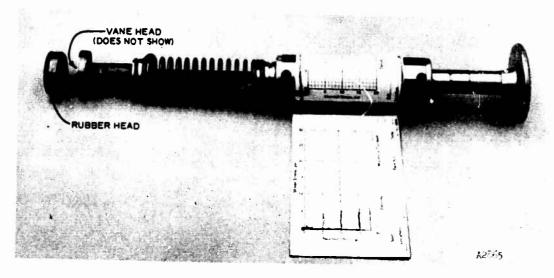


Fig. 4. Cohron sheargraph

Mobility index (MI). A dimensionless number that results from a consideration of certain vehicle characteristics (see Appendix A, Addendum Al, for formulas).

<u>Vehicle cone index (VCI)</u>. The minimum rating cone index (RCI) that will permit a vehicle to complete a specified number of passes, usually one pass and 50 passes.

VCI₅₀ measured. An experimental determination of the minimum RCI of the critical layer required for a vehicle to complete 50 passes. The critical layer for most vehicles is usually the 6- to 12-in. layer below the surface.

VCI₁(50) measured. An experimental determination of the minimum RCI of the critical layer required for a vehicle to complete one pass. The critical layer is the same as that for VCI₅₀, i.e. usually the 6- to 12-in. layer.

VCI_{lt} measured (tentative). An experimental determination of the minimum RCI of the critical layer required for a vehicle to complete one pass. The critical layer for most vehicles is usually the 0- to 6-in. layer.

Maximum drawbar pull (maximum towing force). The maximum amount of sustained towing force a self-propelled vehicle can produce at its drawbar under given test conditions.

Optimum drawbar pull. The towing force that a vehicle produces at its maximum work output.

Work output index.

Work output index = drawbar pull x distance whicle traveled distance wheel or track traveled

Towed motion resistance. The force required to tow a given vehicle in neutral gear under given test conditions.

Acherman steering angle. The acute angle between the left front wheel and the longitudinal axis of the vehicle.

Articulated steering angle. The acute angle between the longitudinal axes of the front and rear vehicle units.

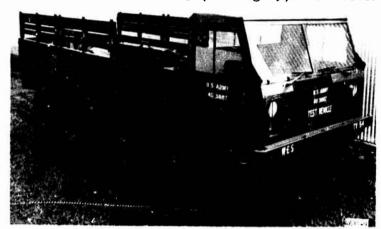
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<u>Slip.</u> The percentage of track or wheel movement ineffective in advancing a vehicle forward.

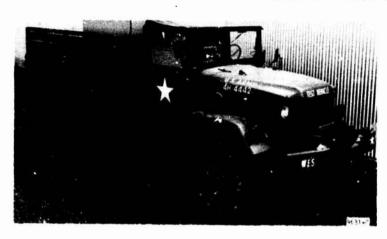
PART II: FIELD TEST PROGRAM

Test Vehicles

7. The wheeled military vehicles tested were the XM410El and the M35A2 (mod) and the tracked vehicle was the M113 (see fig. 5). The MEXA



a. XM410E1



b. M35A2 (mod)



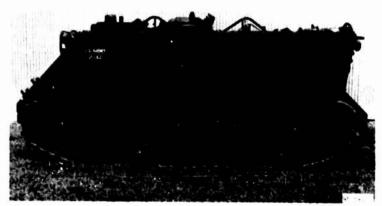
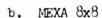


Fig. 5. Military vehicles used in test program

vehicles tested were the MEXA 10x10 and MEXA 8x8 (both wheeled) and the MEXA track (see fig. 6). The modifications to the M35A2 consisted of changing the tires to 11:00x20 NDCC and changing from dual rear wheels to single rear wheels. Pertinent data for the six vehicles are given in



a. MEXA 10x10







c. MEXA track

Fig. o. MEXA vehicles used in test program

- table 1. A more detailed list of vehicle characteristics is given in Report 1 of this series. 5
- 8. As stated previously a preliminary test program was conducted. The purpose of this program was to shake down the MEXA vehicles and to obtain a quick evaluation of their VCI's and those of the M113 and the XM410E1. These preliminary tests included 29 tests at the WES reservation and 5 tests with the XM410El at Chotard Lake. For these tests only, approximate cross-country payloads were placed on the XM410El and M113 and the tires of the XM410E1 were inflated to recommended cross-country inflation pressure. After completion of the preliminary tests, adjustments were made to certain vehicle characteristics to satisfy the requirements of the comprehensive test program as follows. (a) The vehicles' payloads were adjusted to that specified for cross-country or combat operation. The payload of the XM410El was reduced from 7000 to 5000 lb and the payload of the M113 was reduced from 5600 to 4000 lb. (b) Inflation pressure for each tire was adjusted to yield 25 percent deflection for the XM410E1 and M35A2 (mod) and 20 percent deflection for the MEXA 10x10 and 8x8. (The changes in weight and tire pressure were taken into consideration in the analyses of VCI tests.)

Selection, Location, and Description of Test Sites

9. Primary requirements in the selection of the test sites were that the sites (a) be of the same general soil type (clay), (b) be large enough to accommodate several tests, and (c) consist of soil having the range of strength necessary to evaluate the performance of the test vehicles. Also, the estimated cost of testing at a site had to be compatible with the funds available. Several areas were considered. These areas were reconnoitered and after an evaluation of the reconnaissance information, sites that best met the test requirements were selected. It will be recalled that the final selections were two sites at Vicksburg, Miss., and eight near Fallon, Nev.

Vicksburg sites

10. WES Reservation. This site is adjacent to a small upland stream

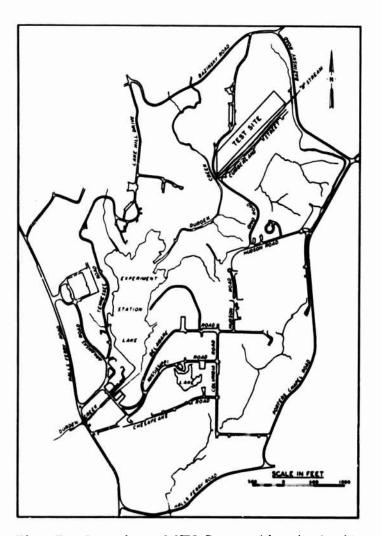


Fig. 7. Location of WES Reservation test site

(B Stream) that flows through the WES Reservation (figs. 7 and 8). site was a soft, relatively level, recent hydraulic fill that varied from 3 to 6 ft in depth; the material for the fill had been pumped from the nearby WES lake. The fill soil classified as fat clay (CH) in the O- to 6in. layer and as lean clay (CL) in the 6- to 18-in. layer according to the USCS (fig. 9). Most of the vegetation (tall weeds) was removed before testing.

11. Chotard Lake.
This test site is on the south bank of Chotard Lake approximately 18 miles northwest of Vicksburg

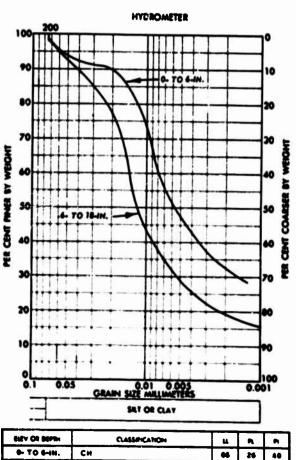
(fig. 10). The water level of the lake rises and falls with that of the Mississippi River, which feeds the lake. At the time of testing the river was low, and a flat expanse of lakeshore was exposed and accessible. The shoreline for a distance of about 400 ft from the lake was practically devoid of vegetation. Inland from this open area was an area that extended for about 300 yd on which willow trees with trunk diameters ranging from to 10 in. were growing. Views of the site are shown in fig. 11. Tests were conducted in both the open and wooded areas. The soil to a depth of 18 in. was classified as fat clay (CH), according to the USCS (fig. 12).

12. Carson Sink. Carson Sink is a large, flat, barren playa,



Fig. 8. WES Reservation test site

Fig. 9. Soil gradation curves and classification data, WES Reservation test site



6124 O4 86434	CLASSIFICATION	u		
0- TO 6-IN.	CH	66	26	40
6- TO 18-IN.	CL	49	23	26

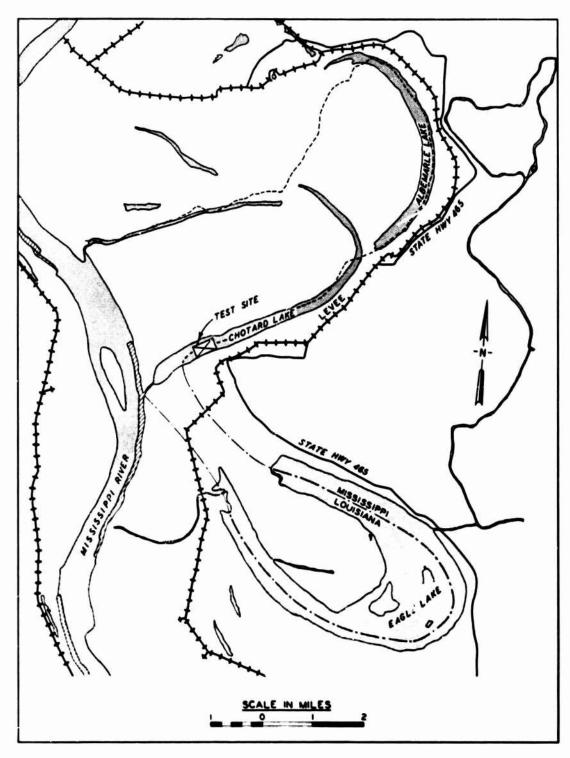


Fig. 10. Location of Chotard Lake test site

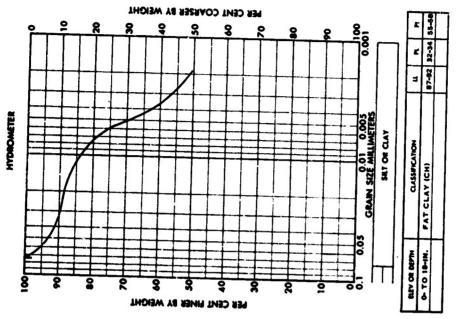
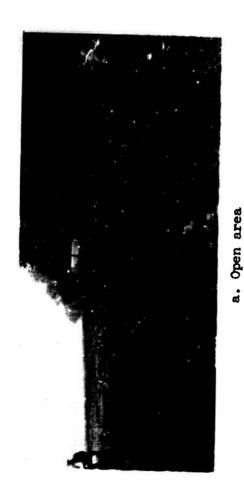
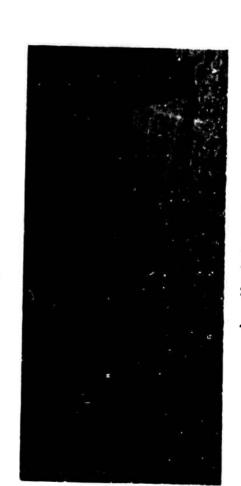


Fig. 12. Soil gradation curve and classification data, Chotard Lake test site





b. Wooded area

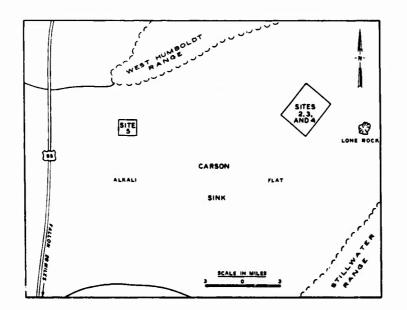


Fig. 13. Location of Carson Sink test sites

covering about 400 square miles. It is located about 20 miles northeast of Fallon (see fig. 13). Carson Sink serves from time to time as a sump for water diverted from the Carson River to relieve flooding of adjacent farmlands and of nearby Fallon National Wildlife Refuge. At the time of testing, most of the ground at Carson Sink was firm and free of surface water. After a thorough investigation of the playa, four sites (see fig. 14), each having a different soil strength, were established and tested. The soil of sites 2, 3, and 4 classified as lean clay (CL) in the 0- to 5-in. layer and as fat clay (CH) in the 5- to 18-in. layer. The soil of site 5 classified as a fat clay (CH) in the 0- to 18-in. layer. (Classifications were in accordance with the USCS.) Soil gradation curves representative of the test sites at Carson Sink are shown in fig. 15.

square miles in area. It is about 20 miles southeast of Fallon (see fig. 16). The western half of the playa was firm and at the time of testing was crisscrossed by numerous drainageways that were 3 to 6 ft deep. In the western half, one site (site 9) was established on a flat between two drainageways. Between the western half (alkali flat) and the eastern half (dry lake) of the playa, a relatively sharp drop in elevation (about 8 ft) occurs. The eastern half serves as a sump for rainwater draining from the Salt Wells Basin and the surrounding mountains. Three test sites (6, 7,

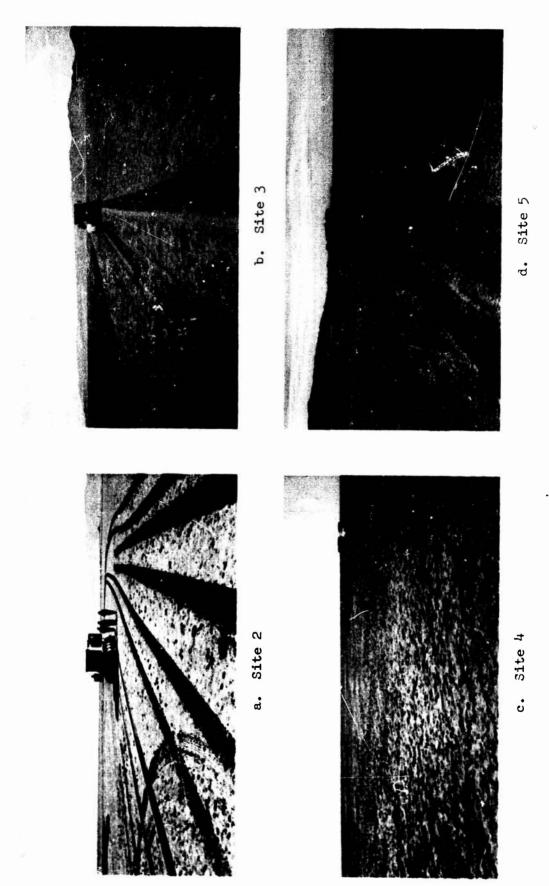


Fig. 14. Carson Sink test sites 2-5

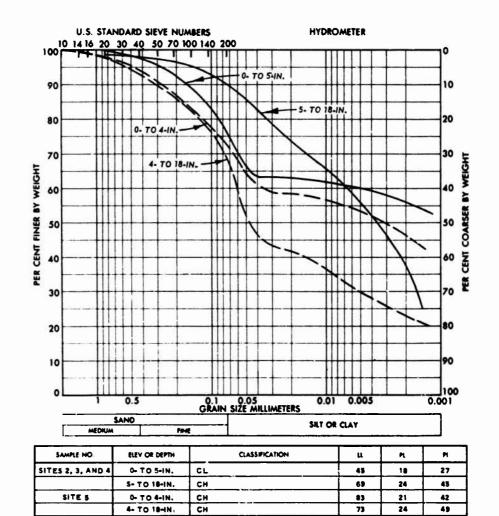


Fig. 15. Soil gradation curves and classification data, Carson Sink test sites

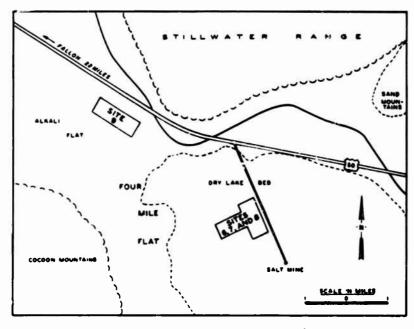
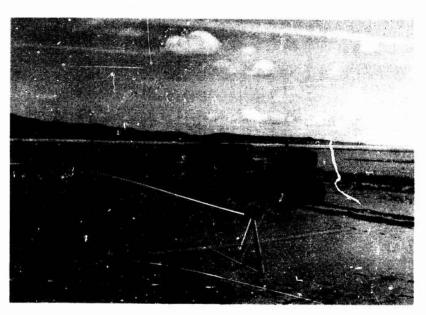
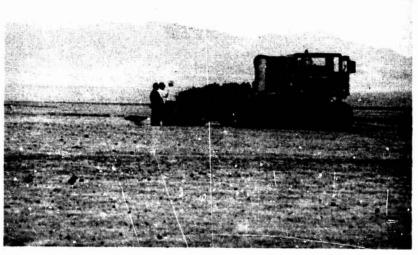


Fig. 16. Location of Four Mile Flat test sites

and 8), each of different soil strength, were established in the eastern half of the playa. At the time of testing, the sites were generally flat, soft, and free of surface water. The soil classified as a fat clay (CH) in the 0- to 18-in. layer. There was a hardpan composed of sand and salt at a depth of 26 to 30 in. that was too firm to penetrate with a hand probe. Views of the sites are shown in fig. 17. A soil gradation curve that is representative of the sites is shown in fig. 18.

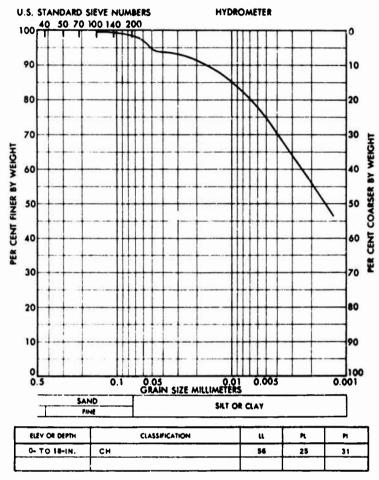


a. Sites 6, 7, and 8



Site 9

Fig. 17. Four Mile Flat test sites 6-9



- 91

Fig. 18. Soil gradation curve and classification data, Four Mile Flat site 6

Test Procedures and Data Collected

YCI determination

the Before traffic began, a 100-ft-long test lane was staked out and come inject at the coil was measured generally at the surface and at 3-in. Vertical increments to a depth of 18 in., and at 24- and 30-in. depths. These measurements were usually male at 10-ft horizontal intervals along the expected paths of the left and right wheels or tracks of the vehicle. In a measurement, where immobilization was unticipated on the first or second para. Initial case inlex readings were actually made in the undisturbed track along the sides of the vehicle after it had become immobilized.

Twenty sets of cone index readings usually were made for each test. In most tests, remolding indexes were measured at two locations beside the test lane (generally at the station where the lowest cone index was recorded) for the 0- to 6-in., 6- to 12-in., and 12- to 18-in. depths. At the remolding index stations, surface shear measurements were made with the sheargraph vane and rubber shear heads. Moisture content and density samples were taken from the surface to a depth of 18 in. at each remolding index station. Representative bulk soil samples were obtained from the surface to a depth of 18 in. for field and laboratory identification. During and after traffic, cone index (at the same horizontal and vertical intervals as those for before-traffic measurements) and rut depths were measured. Observations of the soil and vehicle behavior were recorded during each test.

- 15. Self-propelled tests were conducted to determine the required minimum soil strength for each test vehicle to complete one pass and 50 passes. In these tests, each vehicle was operated in its lowest gear at a track or wheel speed of approximately 2 mph (except on maximum speed passes), and was driven back and forth in 100-ft-long straight-line test lanes until it became immobilized or completed 50 passes.
- Drawbar pull-slip and -speed tests
- 16. Before each drawbar pull test, a test lane large enough to accommodate the test was selected and staked, and a sufficient number of cone index measurements were made to determine that the soil was of the desired strength. Cone index, remolding index, and shear stress were measured, and soil samples for field and laboratory identification and moisture content and density determinations were collected in the same manner as that for the VCI tests.
- 17. Drawbar pull-slip tests were performed by attaching a load cell to a 70-ft-long cable extending from the rear of each test vehicle to the front of a load vehicle. After the test vehicle (operating in its lowest gear) had reached optimum engine rpm (approximately 2 mph) the load vehicle driver increased the load in several stages (by applying the brakes of the load vehicle gradually) from "no load-no slip" to either "high load-high slip" or "power limited" condition (test vehicle did not have sufficient

power to develop 100 percent slip). At all times the test vehicle driver maintained optimum engine rpm. Measurements were made in this manner until a sufficient number of load and slip combinations were recorded to develop a drawbar pull-slip curve.

18. <u>Drawbar pull-speed tests</u> were performed in the same manner as that for drawbar pull-slip tests with one exception: tests were performed at maximum engine rpm in each gear necessary to develop the drawbar pull-speed performance of each vehicle.

Towed motion resistance tests

19. Towed motion resistance tests were conducted in conjunction with drawbar pull tests. With its engine running and transmission disengaged, each test vehicle was positioned so as to straddle one of the rutz developed during the drawbar pull-slip test. The test vehicle was then towed at approximately 2 mph while a continuous record of motion resistance (towed pull) was made.

Speed tests

- 20. Before each test, a test lane of uniform soil strength was selected in the same manner as that for the drawbar pull tests. Additional before- and after-traffic soil strength data were collected in the same manner as that for the VCI tests.
- 21. Each test vehicle began a self-propelled, straight-line test from a standstill (zero speed) condition in its lowest gear and at full throttle and continued through each gear until maximum speed was reached. Then the power train was disengaged, and the vehicle was allowed to roll to a stop.

Maneuver tests

22. Perfore testing began, a section of uniform soil strength large enough to accommodate tests at three different vehicle speeds was staked out. After the test runs were completed, the following data were collected: a planimetric map showing vehicle position markers and the path of turn relative to the approach lane; rut depths; cone index readings in the undisturbed area adjacent to the path taken by the vehicle; cone index readings in the ruts; and sheargraph readings, both at the surface and at the depth of rut. Remolding index and moisture content-density samples were

collected in the same manner as that for the VCI tests.

- 23. A straight-line approach lane, about 300 ft long, was staked out to establish a base line for each test. The test vehicle driver aligned the vehicle in the approach lane and accelerated to the desired speed. Then a ground position marker and data recorder were activated. When the vehicle reached a predetermined spot in the approach lane, the driver turned the vehicle as fast as he could until the maximum steering angle was reached, and at the same time the driver attempted to keep a constant vehicle speed. After maintaining the maximum steering angle and near constant speed through an approximately 180-deg turn, the driver shifted the power train into neutral and allowed the vehicle to roll to a stop. In addition, at most test sites, a test was conducted in which the vehicles were steered into the tightest turn possible while maintaining a speed of approximately 1 mph. The vehicles continued in this manner through a 360-deg turn. Vehicle response measurements
- 24. Each test vehicle was instrumented to provide a continuous record of the desired response measurements during testing. These responses were recorded by a system that included a 36-channel, direct-print oscillograph and two 4-channel amplifier units. The system, together with an alternating current power supply, was installed on the bed of each test vehicle. A detailed description of the instrumentation system is given in Report 1 of this series. The following tabulation shows the type of test and the measurements used in the analysis.

Type of Test	Measurements Made
Drawbar pull	Drawbar pull; drive-line torque; distance traveled by vehicle; distance traveled by wheel or track; time; vehicle speed
Towed motion resistance	Towed pull; distance traveled by vehicle; distance traveled by wheel or track; time
Speed	Drive-line torque; distance traveled by vehicle; distance traveled by wheel or track; steering angle; vehicle speed; time
	(Continued)

Type of Test

Measurements Made

Maneuver

Drive-line torque; distance traveled oy wheel or track; event marks coinciding with ground position markers; steering angle; time; vehicle speed (these measurements were excluded on 360-deg turn test, see paragraph 23)

PART III: DATA ANALYSES

25. The test data were analyzed to determine the relations between soil strength measurements and certain vehicle performance parameters. The relations to be determined were: (a) number of passes completed by vehicle versus soil strength, from which VCI's for one pass and 50 passes were determined, (b) vehicle speed versus drawbar pull, (c) drawbar pull versus slip, (d) drawbar pull versus soil strength, (e) towed motion resistance versus soil strength, (f) vehicle speed versus time (acceleration and deceleration), (g) maximum speed versus soil strength, (h) turning radius versus speed, (i) force versus steering angle, and (j) force versus soil strength. The data analyses are presented in the following paragraphs, together with a discussion of the performance of the MEXA vehicles' articulated steering and inching systems in soft soil.

VCI Tests

26. Eighty-six VCI tests were conducted at sites near Vicksburg, Miss., and Fallon, Nev. A summary of soil data and test results is given in table 2. The relations developed from these test results are discussed in the following paragraphs.

Determination of VCI for 50 passes

27. Previous trafficability studies in fine-grained soils have shown that the performance of most wheeled and tracked vehicles in terms of gono go for 50 passes can be related to soil strength in terms of RCI. The RCI that is just adequate to support 50-pass traffic of a particular vehicle is designated as the 50-pass vehicle cone index (VCI₅₀). Furthermore, test results have shown that there is a 6-in.-thick soil layer whose RCI best relates to vehicle performance. This layer is designated as the critical layer. The depth of the critical layer is dependent upon vehicle weight and the characteristics of the soil's RCI profile. If the critical layer and the 6-in. layer below the critical layer have the same RCI or show an increase in RCI with depth, the strength profile is considered normal. If the 6-in. layer below the critical layer has an RCI less then

that of the normal critical layer, the RCI is considered abnormal and the 6-in. layer below the normal critical layer is used as the critical layer. The normal 50-pass critical layer for the vehicles considered in this study was the 6- to 12-in. layer.

- 28. The RCI of the critical layer is plotted versus the number of passes completed by each vehicle in plate 1. In these plots a clear-cut separation of immobilization and nonimmobilization was not always present. Therefore, the final selection usually produced a measured (experimental) VCI₅₀ that was slightly conservative.
- 29. XM+10E1. Test data are plotted in plate 1, fig. a, for this vehicle. Seven tests resulted in immobilizations and five tests resulted in the completion of 50 passes. Fig. 19 shows test 36 (item 4*) at Chotard Lake in progress. The XM410E1 completed 50 passes with ease in item 12 on an RCI of 32. In item 9 on an RCI of 26 the vehicle had considerable difficulty during the 50th to 54th passes. In item 10 on an RCI of 24 (just 2 RCI less than item 9), the vehicle became immobilized on the 17th pass. From these tests the experimental VCI₅₀ was determined to be a conservative value of 32.
- 30. It should be noted that in items 1-5 (the preliminary tests described in paragraph 8) the vehicle test weight was 18,504 lb (12.1 percent greater than for the other tests). Because of the weight differential the test results of items 1-5 were not given as much consideration as the results of the other tests to determine VCI₅₀ (and one-pass VCI's, discussed subsequently).
- 31. MS5A2 (mod). Fourteen tests were conducted with this vehicle. These data are plotted in plate 1, fig. b. In item 13 on an RCI of 46 and in item 15 on an RCI of 44 th M35A2 became immobilized on the 41st and 47th passes, respectively. In item 14 on an RCI of 55 the vehicle completed 50 passes with some difficulty. Then in item 26 the M35A2 completed

^{*} To facilitate the analysis of data and the presentation of data in tables, plates, etc., the tests were grouped according to type of test, vehicle, and test weight. Sequential "item" numbers were then assigned to the tests. In the remainder of the report, a test is identified by its corresponding item number.



a. After 1 pass



b. After 35 passes



c. After 50 passes

Fig. 19. VCI test in progress at Chotard Lake, XM410E1 (item 4)

50 passes with ease on an RCI of 59. From these tests the experimental VCI_{50} was placed at 56.

- 32. <u>Mll3.</u> Data from 15 tests conducted with the Mll3 are plotted in plate 1, fig. c. In item 39 on an RCI of 30 and in item 33 on an RCI of 27, the Mll3 made 50 passes with little difficulty. In item 37 on an RCI of 22 the Mll3 became immobilized on the 51st pass. Then, considering also the results of items 28 and 38, the experimental VCI₅₀ for the Mll3 was conservatively placed at 29.
- 33. In items 27-32, the test weight of the Mll3 was 24,200 lb (7.1 percent greater than for the other tests). Because of the weight differential the test results of items 27-32 were not given as much consideration as the results of the other tests in determining experimental VCI₅₀ (one-pass VCI is discussed subsequently).
- 34. MEXA 10x10. Eighteen VCI determination tests were conducted with the MEXA 10x10. Test results are plotted in plate 1, fig. d. In item 48 on an RCI of 15 the vehicle was considered to be immobilized on the 47th pass. In item 54 on an RCI of 19, although immobilization appeared to be imminent on the 50th pass, the test was continued through 54 passes without immobilization. Fig. 20 shows this test in progress at Carson Sink site 3. In items 50 and 53, on 22 RCI, 50 passes were completed without difficulty. From the results of these tests the experimental VCI₅₀ was placed at 18.
- 35. In the preliminary tests conducted at Vicksburg, the tire inflation pressure of the MEXA 10x10 was 3.0 psi (average overall deflection of 31.6 percent) while in the comprehensive tests in Nevada tire deflection was set at 20 percent, yielding an average inflation of 7.3 psi. Plate 1, fig. d, indicates that this inflation pressure and deflection differential had little effect on the test results.
- 36. MEXA 8x8. Fourteen VCI determination tests were conducted with the MEXA 8x8. Test results are shown in plate 1, fig. e. Examination of the data shows that the MEXA 8x8 became immobilized in item 61 on an RCI of 20 on the 36th pass. Fig. 21 shows this test at WES in progress. Notes for item 60 show that the vehicle had no difficulty completing 50 passes on an RCI of 21, whereas in item 60 it had extreme difficulty completing

a. After 1 pass





b. After 44th pass

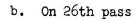
c. After 54th pass

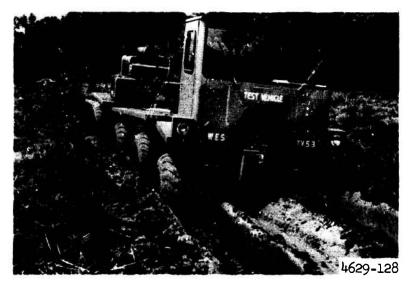


Fig. 20. VCI test in progress at Carson Sink site 3, MEXA 10x10 (item 54)



a. After 1 pass







c. After 36 passes

Fig. 21. VCI test in progress at WES, MEXA 8x8 (item 61)

50 passes on an RCI of 22. Therefore, the separation point between go and no go for 50 passes was placed at an RCI of 23.

- 37. In tests conducted at Vicksburg, the average tire inflation pressure of the MEXA 8x8 was 5.2 psi (average overall deflection of 27.9 percent) while in the Nevada tests, tire deflection was set at 20 percent, yielding an average inflation pressure of 9.0 psi. Plate 1, fig. e, indicates that this inflation pressure and deflection differential had little effect on results of these tests.
- 38. MEXA track. Data for the 13 tests conducted with this vehicle are plotted in plate 1, fig. f. Ten tests resulted in immobilizations and three resulted in completion of 50 passes. In item 81 on an RCI of 20, the MEXA track was immobilized on the 44th pass. In item 83 on an RCI of 19 and in item 86 on an RCI of 20, the vehicle had considerable difficulty completing 50 passes. However, in item 82 on an RCI of 19, 50 passes were completed without difficulty. In item 83 the vehicle was allowed to continue through 54 passes without becoming immobilized. Based on these tests the experimental VCI₅₀ was conservatively placed at 21.
- 39. Summary of VCI50 results. The following tabulation summarizes the results of experimental VCI50 determination:

Vehicle	Experimental VCI 50	<u>Vehicle</u>	Experimental VCI 50
XM410E1	32	MEXA 10x10	18
M35A2 (mod)	56	MEXA 8x8	23
M1 3	29	MEXA track	21

Determination of VCI for one pass

40. Most of the field test evidence collected to date in fine-grained soils indicates that one-pass go vehicle performance separates well from one-pass no-go vehicle performance on the basis of RCI. However, critical-layer criteria based on tests of a range of vehicles and varying RCI conditions have yet to be firmly established. There has been limited evidence indicating that the critical-layer criteria for 50 passes can be used in determining one-pass VCI for some vehicles with generally fair success; a determination of one-pass VCI based on the 50-pass critical-layer

criteria (hereafter referred to as $VCI_1(50)$) is discussed in the following paragraph.

- 41. Measured (experimental) ${\rm VCI}_1(50)$ is shown in plate 1 in the plot for each vehicle. The plots reveal that for the majority of the tests there was generally satisfactory separation of go tests from one-pass no-go tests at the designated experimental ${\rm VCI}_1(50)$ for the XM410E1, M35A2 (mod), M13, and MEXA track. However, it is apparent from examination of plate 1, figs. d and e, that experimental ${\rm VCI}_1(50)$ is a poor indicator of one-pass performance for the MEXA 10x10 and MEXA 8x8. The test data for the MEXA 10x10 show that in five tests the vehicle completed between 1 pass and 39 passes on soils of strengths less than experimental ${\rm VCI}_1(50)$. The MEXA 8x8 test data show that on six tests the vehicle completed between 2 and 27 passes on soils of strengths less than experimental ${\rm VCI}_1(50)$. This suggests that the use of the present 50-pass critical-layer criteria in determining one-pass performance is not satisfactory for all vehicles. These results thus led to the data analysis presented in the following paragraphs.
- 42. Possible one-pass critical-layer criteria for the vehicles in the program were studied in plots (not included herein) of CI and RCI of the 0- to 6-in., 3- to 9-in., 6- to 12-in., 9- to 15-in., 12- to 18-in., and 0- to 12-in. layers, and of combinations of layers versus number of passes completed. The data in these plots were analyzed to find the layer that showed the best separation on the basis of go and no-go performance. The best overall one-pass critical-layer criteria for the six test vehicles were as follows: the 0- to 6-in. layer was considered to be the normal critical layer unless the RCI of the 6- to 12-in. layer was less than that of the 0- to 6-in. RCI, in which case the 6- to 12-in. layer was considered to be the critical layer.
- 43. For each test, the number of passes completed versus the RCI based on this tentative critical-layer criteria was plotted by vehicle in plate 2. (Hereafter the one-pass VCI based on the tentative critical-layer criteria is designated as VCI_{1t}.) The results are discussed in the following paragraphs. Figs. 22 and 23 show typical VCI test immobilizations.
- 44. <u>XM410E1</u>. Test data for the XM410E1 are plotted in plate 2, fig. a. In determining measured (experimental) VCI_{1t} for the vehicle, more



a. XM410El was immobilized on 7th pass at Chotard Lake (item 5)

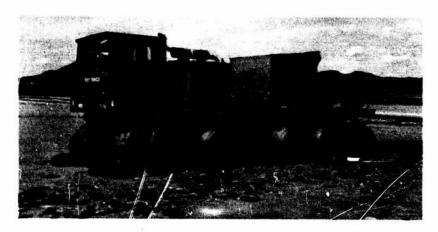


b. M35A2 (mod) was immobilized on 2d pass at Carson Sink site 2 (item 19)



c. Mll3 was immobilized on 1st pass at Four Mile Flat site 6 (item 41)

Fig. 22. Typical VCI test immobilizations, military vehicles



a. MEXA 10x10 was immobilized on 1st pass at Four Mile Flat site 7 (item 55)



b. MEXA 8x8 was immobilized on 1st pass at Four Mile Flat site 6 (item 72)



c. MEMA track was immobilized on 2d pass at Four Mile Flat site 8 (item 85)

Fig. 23. Typical VCI test immobilizations, MEXA vehicles

consideration was given to items 8, 7, 11, and 10 than to the other items. The XM410El was immobilized during item 8 on an RCI of 10 on the first pass and was immobilized in item 7 on an RCI of 17 on the 14th pass. However, because of the low immobilization pass number (fourth pass) in item 11 on an RCI of 21, the experimental VCI_{1t} was placed at 18.

45. M35A2 (mod). Plate 2, fig. b, shows a plot of test data for the M35A2 (mod). In item 22 the vehicle was immobilized on the first pass on an RCI of 22. In item 16 it was immobilized on an RCI of 24 on the fifth pass, whereas in item 19 it was immobilized on an RCI of 26 on the second pass. Then in item 18 on an RCI of 29 and in item 21 on an RCI of 30 the M35A2 (mod) was immobilized on the ninth and fourth passes, respectively. Based on these test results, the experimental VCI_{1t} was placed at 27.

46. M13. The RCI-number of passes completed relation for the M13 is shown in plate 2, fig. c. In item 40 on an RCI of 11, immobilization occurred on the first pass. Notes for this item indicate that had the soil strength been slightly higher, the M13 probably would have been able to complete one pass. Considering test results in items 30, 31, 32, 34, and 36, the experimental VCI₁₊ was placed at 15.

47. MEXA 10x10. Test results for the MEXA 10x10 are shown in plate 2, fig. d. In items 55 and 58 on an RCI of 6 the MEXA 10x10 was immobilized on the first pass. Then in items 59 and 47 on an RCI of 8 the vehicle was immobilized on the third and sixteenth passes, respectively. Based on these test results, the experimental VCI_{1t} was placed at 7.

48. MEXA 8x8. Test results for this vehicle are shown in plate 2, fig. e. In item 71 on an RCI of 10 the MEXA 8x8 was immobilized on the fifth pass; however, on this same RCI the test vehicle immobilized on the first pass in item 70. In items 63 and 73 on an RCI of 12 the MEXA 8x8 was immobilized on the third and fourth passes, respectively. Consideration was also given to item 62 in which the vehicle was immobilized on the eleventh pass on an RCI of 13. Based on these test results, the experimental VCI_{1t} for the MEXA 8x8 was placed at 11.

49. MEXA track. The RCI-number of passes completed relation for the MEXA track is shown in plate 2, fig. f. In item 74 the vehicle was immobilized on the first pass on an RCI of 5. In item 77 and item 84 the MEXA

track was immobilized on the second and sixth passes, respectively, on an RCI of 6. Based on these results and considering the results of items 78, 75, and 76, the experimental VCI_{1t} for the MEXA track was placed at 7.

50. Summary of VCI_{lt} results. The following tabulation summarizes the results of experimental VCI_{lt} determinations:

Vehicle	Experimental VCI		Experimental VCI _{lt}
XM410E1	18	MEXA 10x10	7
M35A2 (mod)	27	MEXA 8x8	11
M13	15	MEXA track	7

51. In review, the experimental VCI_{lt}'s shown above were determined on the basis of the critical-layer criteria described in paragraph 42. These criteria were best for determination of the minimum soil strength that would permit the vehicle to make one pass. For the remaining vehicle performance parameters (drawbar pull, motion resistance, etc.), where soil strengths were, for the most part, greater than experimental VCI_{lt}, the 0-to 6-in. RCI correlated best with performance. Therefore, the following analyses are on the basis of 0- to 6-in. RCI.

Drawbar Pull Tests

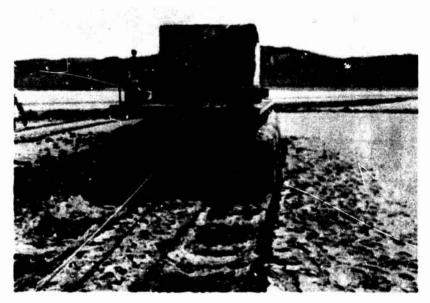
52. Sixty-three drawbar pull tests were conducted, 6 on asphalt pavement and 57 on a range of soil strengths at test sites in Nevada. Fig. 24 shows vehicles in position for drawbar pull tests. Soil strength and related data for each test are summarized in table 3. Drawbar pull, torque, speed, and slip data for each test are summarized in table 4. In the following paragraphs, the relations of drawbar pull to speed, slip, and RCI of the 0- to 6-in. layer are discussed.

Drawbar pull-speed relations

53. For each drawbar pull-speed test, drawbar pull in terms of drawbar pull coefficient (drawbar pull, D, in pounds divided by vehicle weight, W, in pounds) was plotted versus speed, and curves of best visual fit were drawn through the data points. The curves are shown in plates 3 and 4.



a. Carson Sink site 3, MEXA track (item 137)



b. Four Mile Flat site 6, MEXA 10x10 (item 119)

Fig. 24. MEXA track and lOx10 in position prior to start of drawbar pull tests

(Because of the large amount of data, the measured points are shown in the M35A2 (mod) plot only.) The relations shown represent the maximum drawbar pull available for a given vehicle speed and a particular soil strength in terms of 0- to 6-in. RCI. The inflections in the curves indicate optimum speed for gear changes.

54. These curves show that, in general, as soil strength decreases

maximum drawbar pull at a given speed decreases. At speeds between 3 and 6 mph on soil strengths of 52 RCI and above, the MEXA 10x10 was able to develop drawbar pull values slightly higher than those developed on pavement (see plate 4, fig. a, items 110 and 114). Higher drawbar pull tests were not attempted with the MEXA 10x10 and MEXA 8x8 on pavement because mechanical failures of the MEXA 8x8 (see paragraph 63) had occurred at high drawbar pulls in tests on soils (items 123 and 128). At speeds less than about 8 mph the MEXA track developed higher drawbar pull values on soil than those developed on pavement (see plate 4, fig. c, items 133 and 139).

Drawbar pull and work output index versus slip

55. Drawbar pull in terms of drawbar pull coefficient D/W versus wheel or track slip for each test was plotted and curves of best visual fit were drawn through the data points. An example of these plots is shown in fig. 25; D/W is represented by the solid line.

56. Since D/W varies with slip, the maximum D/W is a performance

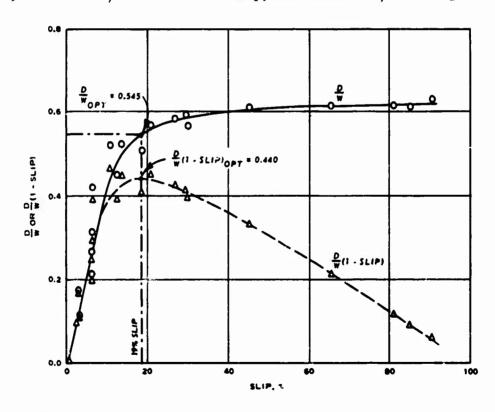


Fig. 25. Drawbar pull versus slip, MEXA 8x8 (item 126)

parameter often used in evaluating the traction capabilities of vehicles. However, in clay soils, the maximum drawbar pull usually occurs at or near 100 percent slip. At 100 percent slip, maximum D/W is not a meaningful parameter because no useful work can be done when a vehicle is not moving forward. A more meaningful performance parameter is the optimum D/W value, the value of D/W when the vehicle's work output index is at maximum. Work output index is a dimensionless number that indicates the vehicle's towing efficiency and is defined as follows:

Work output index =
$$\frac{D}{W} \times \frac{\text{distance}}{\text{distance tracks or}} = \frac{D}{W}(1 - \text{slip})$$
wheels traveled

Optimum D/W values were determined from plots of D/W and work output index versus slip. An example is shown in fig. 25. Wheel or track slip at which the maximum work output index occurs is termed optimum slip.

57. RCI of the O- to 6-in. layer, optimum drawbar pull $(D/W)_{\rm opt}$, and optimum slip for each test used in the analysis are as follows:

	0- to	Opti Drawba	r Pull	Opti-		0- to		imum ar Pull	Opti-		0• to		imum er Pull	Opti-
Item No.	6-in. RCI	16	(D/W) _{opt}		Item No.	r-in.	1b	(D/W) _{opt}	Slip	Item No.	ecin.	1b	(2 /v.) cb.	Flip
		10M410E1			ļ		MEXA 10	10		1	MEXA	ex ^e (Cor	tinued)	
87	50	9.750	0.53	10	107	52	12,260	0.62	20	125	49	13.00	0.72	24
88	50	8,590	0.52	16	102	35	11,720	05	.20	120	13	3.040	0.10	•)
59	37	7.425	0.45	19	100	35	12,620	0.70	23	130	1.2	2, 450	0.15	20
90	3.4	6.270	7. 3 ²²	20	110	52	12,620	0.70	19	131	11.	1.710	0.04	2
91	24	3,300	0.20	25	111	23	9,655	0.44	50	1				
92	24	3,300	0.20	19	l					1		MEIXA Tras	×	
03	•	9.054	0.55**	5**	112	-, 4	9.735	0.5	50	İ				
					113	162	12.050	0.67	19	135	52	15,155	^.	15
		M35A2 (m	<u>×!)</u>		114	1:2	12.520	0.70	10	133	53	14,350	o	15
			_		115	13	2.345	0.13	311	1.34	55	15. 14)	0. * *	15
Ale	50	9.425	0.52**	54 • •	116	15	2 349	9.1	23	135	3.2	12. "	5. 5	7.3
95	50	1.75	0.52**	50**						2.34	5.	12,5 %	1. 1.	16
#	37	5.25	0.2)	24	11"	:3	11,900	0	1					
97	3.7	4.555	0.25	5.5	114	17	7,300	0.41	21	137	2, 4	15. 587	7	1 4
15	17.2	10.570	0.53	35	11 4	1€	5. 70	0.35	1-	15"	15+	12,110	3.	
145	•	11,3000	()	15**	1.20	10	3 44	0.1	50	1 * *	120	14,110	0. 12	1 4
					121	11	2,525	0.14	1.	140	4	14.1 0	9. 12	
		M11 ·			12.	12	2,525	0.14	24	141	47	12,900	7	11
93	54	14,400	1 . 2	20.00	1		MEXA TO	ec.		124.5	1.	1.433		100
100	5.	12,150	0.54**	1: **	ł			_		14.	•	4. 18.0	2.31	41.3
101	47	12,150	3.54	1 *	123	5 4	12,300	3.05	1 .	144	*	1.5		• •
102	3 "	11, 200	0.50	15	124	26	2,226	0.35	15	14.7	•	F = 1	1, 5	1.
105	- 4	4. 7.73	3.43	1.	1.35	20,	2.15) ~	1-	1				
					1.4	2.	1 3 . 2 ()	0.54	1 .					
104	.24	10.5 %	3.4	1	15.	2 1	11, -3			Í				
10.	15	4.15	0.14	1 **	ì					ì				
10-	1 ~	4.5.0	20	.AO										
14.	•	14,4000	J	5**						i				

^{*} Pavement.

* Vehicle reached its "power limit" before = 0 %) and was achieved. When the power from all a behing count levely enough force to produce 105° slip between its trability elements and a partituder go and condition it is said to have reached its power limit.

(D/W)_{opt} versus O- to 6-in. RCI

- 58. $(D/W)_{\rm opt}$ is plotted versus 0- to 6-in. RCI in plate 5. The experimental VCI_{1t} for each vehicle is also shown plotted as an x at zero $(D/W)_{\rm opt}$. With the experimental VCI_{1t} values as guides, curves of best visual fit were drawn through the data points. Test results are discussed in the following paragraphs.
- 59. $\underline{XM410E1}$. Item 93 was conducted on pavement with tires of the XM410E1 inflated to an average pressure of 35 psi. In this test the XM410E1 reached its power limit (the vehicle's engine stalled) developing a maximum D/W of 0.55 at 5 percent slip. Six drawbar pull tests were conducted on soil with the tires inflated to 12.2 psi. In items 87 and 88, the XM410E1 reached its power limit between 15 and 20 percent slip. The D/W and work output versus slip curves for these tests indicated that $(D/W)_{opt}$ values developed near the vehicle's power limit. The 0- to 6-in. RCI versus $(D/W)_{opt}$ for each test is plotted in plate 5, fig. a. The curve on this plot shows a sharp increase from zero to 0.47 $(D/W)_{opt}$ between an RCI of 17 and 50. Beyond an RCI of about 50 there was little increase in $(D/W)_{opt}$ with increase in soil strength.
- 60. M35A2 (mod). Six drawbar pull tests were conducted with the M35A2 (mod). The M35A2 (mod) reached its power limit (the vehicle's engine and wheels stalled) in the pavement test (item 145) and in soil test items 94 and 95. In the pavement test, the M35A2 (mod) developed a maximum D/W of 0.62 at 13 percent slip. In items 94 and 95, the M35A2 (mod) reached its power limit between 20 and 30 percent slip. The D/W and work output versus slip curves for these tests indicated that the (D/W)_{opt} values were achieved near the vehicle's power limit. The RCI versus (D/W)_{opt} curve in plate 5, fig. b. shows that between 27 and 50 RCI (D/W)_{opt} increased sharply from hero to 0.52. Beyond about 50 RCI, (D/W)_{opt} increased gradually with increase in soil strength.
- oi. Mil3. Nine drawbar pull tests were conducted with the Mil3. The vehicle reached its power limit (the vehicle's tracks stalled but the engine did not) in the pavement test (item 146) and in two soil tests (items 99 and 100). In the pavement test, the Mil3 reached its power limit leveloping a maximum D/W of 0.64 at about 2 percent slip. In items 99

and 100, the M113 reached its power limit at 28.0 and 23.8 percent slip, respectively. In plate 5, fig. c, the RCI- $(D/W)_{\rm opt}$ curve is steep between a $(D/W)_{\rm opt}$ of zero and 0.50, indicating a great increase in pull between 15 and 50 RCI. Beyond 50 RCI there is only a gradual increase in $(D/W)_{\rm opt}$ with increase in soil strength.

- MEXA 10x10. Sixteen drawbar pull tests were conducted with the MEXA 10x10. Plate 5, fig. d, is a plot of $(D/W)_{\rm opt}$ versus RCI for the MEXA 10x10. The plot shows that as RCI increased from 7 to 35, $(D/W)_{\rm opt}$ increased from 0 to 0.65. Values of $(D/W)_{\rm opt}$ increased only slightly between 65 and 162 RCI. The MEXA 10x10 had sufficient power to produce 100 percent slip in all tests. In item 110, the MEXA 10x10 developed a maximum pull of 18,328 lb $(1.02\ D/W)$ at 100 percent slip (see table 4).
- 63. MEXA 8x8. RCI versus (D/W)_{opt} data for nine drawbar pull tests conducted with the MEXA 8x8 are shown in plate 5, fig. e. The curve shows an increase in (D/W)_{opt} from zero to 0.62 between 11 and 45 RCI. In item 123 the MEXA 8x8 developed a maximum pull of 18,316 lb (0.96 D/W). At this pull, Nos. 3 and 4 differentials failed and had to be replaced. Furthermore, in item 128 the Nos. 3 and 4 differentials failed at 0.71 D/W. Because of these costly mechanical failures, high drawbar pulls on firmer soils and on pavement were not attempted.
- 64. MEXA track. RCI versus (D/W)_{opt} data for the 14 tests conducted with the MEXA track are shown in plate 5, fig. f. The plot shows an increase in (D/W)_{opt} from zero to 0.65 between 7 and 35 RCI. Beyond 35 RCI, (D/W)_{opt} increased gradually with increase in soil strength. The MEXA track had ample power to generate 100 percent slip at the tracks in all tests. In item 133, the MEXA track had a maximum of 1.02 D/W at 100 percent slip. In the pavement test (item 149) the MEXA track was able to pull 0.87 D/W at 21.1 percent slip; had the cable between the load vehicle and test vehicle not failed in this test, higher pull and slip values probably would have been developed.

Towed Motion Resistance

65. The towed motion resistance for each vehicle was measured following most drawbar pull tests. A summary of the soil data for each test

is presented in table 3. One-pass towed motion resistance (in pounds and as a coefficient R/W where R equals motion resistance in pounds and W equals vehicle weight in pounds) and 0- to 6-in. RCI for each test are tabulated below. The coefficient R/W and the RCI for each test are plotted in plate 6. A curve of best visual fit was drawn through the data points.

Item No.	0- to 6-in. RCI	Motion	Resistance Coefficient R/W	Item	O- to 6-in. RCI	Motio	n Resistance Coefficient R/W
	XM41	OE1			MEXA 10x10	(Conti	nued)
87 89 91 153 93	50 37 24 189 Pavement	1565 215 0 3225 992 592	0.09 0.13 0.20 0.06 0.04	111 113 115 122 147	23 162 1.3 12 Pavement	1490 770 1545 1750 561	0.08 0.04 0.09 0.10 0.03
	M35A2	(mod)		ļ	<u>MEXA</u>	8x8	
94 96 98 1 45	50 37 1 7 2 Pavement	2062 3500 1373 726	0.11 0.19 0.08 0.04	124 126 128 148 130	25 29 49 Pavement 13	1680 1575 1325 641 3323	0.09 0.08 0.07 0.03 0.17
	<u>M</u>	13		131	14	4172	0.22
99 1 0 1	53 37	1821 2780	0.08 0.12		MEXA	Track	
103 161 146	24 189 Pavement	3560 1469 1024	0.16 0.06 0.04	132 134 136 138	52 32 23 159	1800 2020 2360 1500	0.09 0.10 0.12 0.08
	MEXA	10x10		149	Pavement	1136	0.06
108 110	35 52	1260 750	0.07 0.04	144	16 6	652 0 9 07 0	0. 33 0. 46

XM410E1, M35A2 (mod), and M113

66. In plate 6, figs. a, b, and c, the test data for the XM410E1, the M35A2 (mod), and the M13 show that an R/W of 0.04 was measured on pavement. Then the curves show a gradual increase in R/W from pavement to an RCI of about 50. Below about 50 RCI, R/W increased rapidly with little decrease in RCI. The lowest strengths tested show an R/W of 0.20 on 24 RCI for the XM410E1, an R/W of 0.19 on 37 RCI for the M35A2 (mod),

and an R/W of 0.16 on 24 RCI for the M113.

MEXA 10x10

67. In plate 6, fig. d, the MEXA 10x10 curve shows an R/W of 0.03 on pavement. Below pavement strength, R/W increased little as RCI decreased to about 30. From an RCI of 30 to an RCI of 12, R/W increased gradually from 0.06 to 0.10.

MEXA 8x8

68. The MEXA 8x8 curve, plate 6, fig. e, indicates a gradual increase from pavement R/W (0.03) to an RCI of about 30. Below about 30 RCI, the curve shows that R/W increased rapidly to 0.22 at 12 RCI.

MEXA track

69. In plate 6, fig. f, the MEXA track data show an R/W of 0.06 on pavement. This, the highest R/W measured on pavement for the vehicles tested, reflects the mass of the MEXA track's track system. R/W increased gradually as strength decreased from pavement to an RCI of 30. Below about 30 RCI, the curve shows that R/W increased rapidly to 0.46 at an RCI of 6.

Speed Tests

- 70. Forty-four speed tests were conducted, nine on pavement and 35 on a range of soil strengths, at Vicksburg and Fallon. Soil strength and related data for each test are summarized in table 5. Each test was conducted as described in paragraph 21. The relations developed for each vehicle are shown in plates 7 and 8 as speed versus time. Only curves are shown since the individual data are numerous; however, the data are on file at WES. These curves were used principally to obtain maximum speed-soil strength relations; however, measures of acceleration and deceleration can be obtained. A detailed analysis of acceleration and deceleration is not within the scope of this report; therefore, these performance parameters are discussed in general terms and no attempt is made to relate them to soil strength in this analysis.
- 71. Once maximum speed was believed attained, the driver disengaged the power train and allowed the vehicle to roll to a stop. Deceleration portions of the speed-time curves in plates 7 and 8 are more clearly

defined than are the acceleration and time required to reach maximum speeds. There should be a relation between slopes of deceleration curves and soil strength, and also the deceleration curves should be straight lines if the only factor afferting deceleration were soil strength. However, in some cases, pavement tests in particular, the deceleration curves are convex in shape. One of the additional factors that probably affected deceleration is wind resistance; however, further study will be required before definite relations can be developed.

Maximum speed versus soil strength

72. The maximum vehicle speeds and soil strengths in terms of the 0- to 6-in. RCI used in the analysis are as follows:

			Vehicle	ļ			Vehicle
Item	0- to ό-in. RCI	Maximum Speed mph	Range and Transmission*	Item	0- to 6-in. RCI	Maximum Speed mph	Range and Transmission*
		<u>XM41</u>	OE1	İ	ME	XA 10x10 (C	ontinued)
152 151 150 153 1%	24 35 49 189 Favement	24.1 28.5	L-1, L-2, L-3 L-1, L-2, L-3 L-1, L-2, L-3 H-1, H-2 H-1, H-2, H-3	168 166 190 191	69 17 ¹ 4 Pavement Pavement	17.3 21.3 20.9 22.5**	H-1, H-2 H-1, H-2 H-1, H-2 H-1, H-2
		M35A2	(mod)				
157 157 157 157 167 16	35 35 49 189 Payement Favement	14.4 25.9 3).5	I1, I2 I1, I2 I1, I2, I3 I1, I2, I3, I4, I5 II1, II2, II3, II4, II5 III. III2, II3, II4, II5	177 176 173 175 174 170 173	12 12 13 15 16 19 21	4.9 7.2 9.7 7.2 8.4 12.0	H-1, H-2 L-1, L-2 H-1, H-2 L-1, L-2 L-1, L-2 H-1, H-2 H-1, H-2
		<u> 1</u>	<u>n13</u>	172 169	29	16.2 14.7	H-1, H-2
1/2 1:0 100 100	18 24 35 50	7.3 10.3 15.4 17.3	1-2 1-2 1-2, 3-5 1-2, 3-5	171 192 193	33 49 Favement Favement	16.3 22.2 22.9**	H-1, H-2 H-1, H-2 H-1, H-2 H-1, H-2
1: 1 1# :	179 Invenent	20.	1-2,			MEXA Tr	ack
	11 20	DE WA		184 183 181 180 179 182 189	10 24 31 49 103 Pavement	2.2 3.5 10.6 11.0 12.2 15.6 11.2	L-1, L-2 I-1, L-2 H-1, H-2 H-1, H-2 H-1, H-2 H-1, H-2

I had I denote low and high, respectively.

The conjugate with tires inflated to pressures recommended for use on hard-surface roads

The conjugate with tires inflated to pressures recommended for use on hard-surface roads

The conjugate with tires in Market (mod), 70 roi: MSEA 10x10, 15 pai; and MEEA fixe, 15 pai).

73. Maximum vehicle speed is plotted versus 0- to 6-in. RCI in plate 9; included in each plot is the maximum vehicle speed achieved on pavement. The maximum speed values were obtained from plates 7 and 8. A curve of best visual fit was drawn through the data points. The dashed portions of the curves were determined by extrapolating between the lowest RCI-maximum speed value and experimental VCI_{1t} - 1 plotted at zero speed for each vehicle. VCI_{1t} - 1 was assumed to be the spil strength that would cause immobilization. Extrapolation between VCI_{1t} - 1 and lowest RCI-maximum speed value was necessary in order to obtain an approximate speed value for VCI_{1t} because of difficulty in locating test sites having soil strengths equal to experimental VCI_{1t} for each vehicle. The the curves show that at VCI_{1t} speed for all six vehicles tested was approximately 2.5 mph. Acceleration and deceleration

74. As can be seen in plates 7 and 8 for a given vehicle and soil strength, uniform acceleration did not develop, generally, because of shifting of gears. Gear shifting can be seen as inflections in the speed-time curves (plate 7, fig. a). In several tests toward the end of the acceleration period, erratic speed-time curves were developed (item 153, plate 7, fig. a); this was not fully explainable and needs further study.

75. The development of relations between acceleration and soil strength is not presented. One of the difficulties in relating acceleration to soil strength is that, of necessity, vehicle range and transmission were varied from test to test. For each test a range and transmission gear were selected to produce maximum vehicle speed, which in some cases did not necessarily provide the maximum acceleration that could be obtained. Furthermore, in some tests deceleration was not started at the proper time. For example, in item 150 (plate 7, fig. a) it appears that deceleration was started before maximum vehicle speed had been reached. Also, in item 152 it is shown that the vehicle reached maximum speed in about 15 sec; however, the driver continued, attempting to regain the maximum speed once speed was reduced. It is probable that the maximum speed was reached in L-2* gear combination and the vehicle shifted into L-3 and speed was

^{*} L-2, etc., denotes low second, etc.

reduced. Had the vehicle continued in L-2, the speed might have been slightly higher.

- 76. XM410E1. Five speed tests were conducted with the XM410E1. In the maximum speed on pavement test (item 186), the XM410E1 tires were inflated to 35-psi pressure (recommended pressure for XM410E1 tires on pavement). In all other XM410E1 tests, the average tire inflation pressure was 12.2 psi. The curve in plate 9, fig. a, shows that as soil strength increased from an experimental VCI_{1t} of 18 to about 50 RCI, speed increased sharply from 2.5 to 22.5 mph. As soil strength increased beyond 50 RCI, speed increased gradually. A top speed of 53 mph was developed on pavement.
- 77. M35A2 (mod). RCI's versus maximum speeds for the M35A2 (mod) tests are shown in plate 9, fig. b. Four tests were conducted on soil and two tests on pavement. In one of the pavement tests (item 188), tire inflation pressure was 70 psi (recommended pavement pressure). In all other tests, average tire pressure was 20 psi. The higher tire inflation pressure increased the maximum speed on pavement of the M35A2 (mod) by 12.8 mph. The curve in plate 9, fig. b, shows an increase in speed from 2.5 to 52 mph between an experimental VCI_{1t} of 27 and pavement.
- 78. M13. Six speed tests were conducted with the M13. The curve in plate 9, fig. c, shows that as soil strength increased from an experimental VCI_{lt} of 15 to about 50 RCI, speed increased sharply from 2.5 to 17.3 mph. Beyond an RCI of 50, speed continued to increase gradually to about 30.2 mph on pavement.
- 79. MEXA 10x10. Eight speed tests were conducted with the MEXA 10x10. Results are plotted in plate 9, fig. d. In item 191 the MEXA tires were inflated to a pressure of 15 psi (recommended pavement pressure). In all other tests the inflation pressure was 7.3 psi. The increased tire inflation pressure increased the MEXA 10x10 maximum speed on pavement by 1.6 mph. The curve shows that as soil strength increased from an experimental VCI_{1t} of 7 to 35 RCI, speed increased from 2.5 to 17.0 mph. Beyond 35 RCI, speed increased gradually to a maximum of 22.5 mph on pavement.
- 80. MEXA 8x8. Speed test data for the 12 tests conducted with the MEXA 8x8 are shown in plate 9, fig. e. In item 193 the MEXA tire inflation pressure was 15 psi (recommended pavement pressure). At this pressure the

MEXA 8x8 reached a maximum speed of 22.9 mph, but in reaching this speed the vehicle's front unit experienced excess lateral movement which caused the driver concern for his safety. However, when inflation pressure was reduced to 9 psi the maximum speed on pavement was decreased by only 0.7 mph and lateral movement of the front unit was not excessive. The curve in plate 9, fig. e, shows an increase in speed from 2.5 to 17.5 mph from an experimental VCI_{1t} of 11 to an RCI of 45, indicating that the MEXA 8x8 is sensitive to small changes in soil strength. Beyond 45 RCI, this sensitivity decreases.

81. MEXA track. Seven tests were conducted with the MEXA track. A plot of the test data is shown in plate 9, fig. f. The curve for these data indicates that as soil strength increased from an experimental VCI_{1t} of 7 to 30 RCI, speed increased sharply from 2.5 to 10.5 mph. Between 30 RCI and pavement, speed increased gradually to a maximum of 16.2 mph.

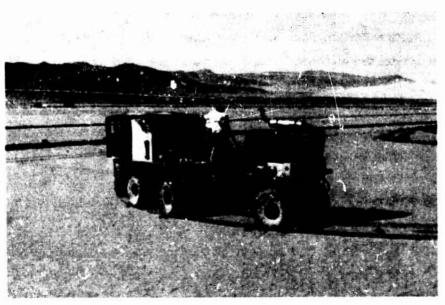
Maneuver Tests

82. At the Carson Sink and Four Mile Flat tests sites 101 maneuver tests were conducted with the six test vehicles on a range of soil strengths. Soil strength and related data for each test are summarized in table 6. The one-pass average speed and measured turning radius for each test are presented in table 7. Also shown in table 7 are steering angle and corresponding torque data for tests with the Ackerman-steered XM110E1 and M35A2 (mod) and with the articulated steering of the MEXA 10x10 and MEXA track. Steering angle and torque data in turning tests with the M13 were not recorded because the M113 is a skid-steer vehicle and it is not equipped with a steering transducer. Steering angle and torque data were recorded in tests with the MEXA 8x8. However, because reduction of the torque record produced negative torque that could not be reconciled in some tests, the data were considered to be questionable and are not included in the analysis. The analysis of the maneuver test data consists of the development of turning radius-speed relations. force-steering angle relations, and force-RCI relations. These relations are presented and discussed in

the following paragraphs. Typical maneuver tests in progress are shown in fig. 26.



a. MEXA 10x10 after completing a left turn at Carson Sink site 4 (item 240)



b. MEXA 8x8 after completing a right turn at Four Mile Flat site 6 (item 271)

Fig. 26. Typical maneuver tests in progress

Turning radius-speed relations

83. Turning radius (in feet) and speed (in miles per hour) data were plotted for each of the test vehicles, and curves of best visual fit were drawn through the data points. These plots are presented in plate 10. The 0- to 6-in. RCI for each turn is also shown in the respective plot. The turning radii were obtained from planimetric maps that show the path taken by the outside edge of the outside wheel or track of the vehicles in each test. The average speed for most turn tests was calculated from measurements of time and distance. The time and distance required for the vehicle to roll to a stop after the vehicle power train was shifted into neutral (paragraph 21) were excluded from the average speed computation.

84. The relations developed in plate 10 show that, in general, for the range of speeds tested, as speed increased turning radius increased. Although there is no indication of a strong correlation between soil strength and turning radius for a given vehicle, it is probable that differences in soil scrength may have contributed to the scatter of the data in plate 10. Also, test procedures created some difficulty in determining the turning radius in some of the tests, and this could account for part of the scatter.

Force-steering angle relations

85. For the XM410E1, M35A2 (mod), MEXA 10x10, and MEXA track, performance in terms of force (at the wheel- or track-ground interface) computed from drive-line torque divided by vehicle weight (F_T /W) was plotted versus steering angle in degrees for each turn test. F_T was computed without regard to efficiency losses between the torque sensor and wheel- or track-ground interface. A curve of best visual fit was drawn through data points for each turn test. The curves were grouped by vehicle according to tests conducted at approximately the same speed and are presented in plates 11 and 12. For each curve (represented by item numbers) the corresponding 0- to 6-in. RCI and the average speed are tabulated below the respective plot.

86. The curves show the relation of steering angle to F_T/W from the straight-line position (0 deg) through the steering action to the maximum steering angle (MSA). These relations indicate that, generally, during

the steering action F_T/W increased very gradually for the wheeled vehicles and gradually for the MEXA track between zero steering angle and about 5 deg less than maximum steering angle (MSA - 5 deg). At about MSA - 5 deg, F_T/W usually began to increase sharply, and in most cases F_T/W reached a maximum at the MSA. Tabulated below are the average MSA for each vehicle, the average increase in F_T/W from zero steering angle to MSA - 5 deg, and the average increase in F_T/W from zero steering angle to MSA. The MSA values shown are average values since the MSA for each vehicle deviated slightly from test to test. This deviation probably was caused by slack in each vehicle's steering system.

Vehicle_	Avg MSA deg	Avg Increase in F _T /W from Zero Steering Angle to MSA - 5 deg	Avg Increase in FT/W from Zero Steering Angle to MSA
XM410E1	29.0	0.02	0.06
M35A2 (mod)	24.5	0.03	0.07
MEXA 10x10	25.9	0.02	0.07
MEXA track	27.2	0.07	0.13

- 87. The tabulation above shows that the increase in F_T/W was about the same between zero steering angle and MSA 5 deg for the three wheeled vehicles, but that for the MEXA track the increase was about double that of the wheeled vehicles. This was also true of the average increase in F_T/W from zero steering angle to MSA.
- 88. As shown in the plots, the curves for each vehicle exhibit the same general shape and tend to separate according to soil strength. The plots show that generally as soil strength decreases, F_T/W tends to increase. The plots also indicate that for the range of speeds tested with a particular vehicle, differences in speed had little effect on forcesteering angle relations.

F_T/W versus 0- to 6-in. RCI

89. Report 3 of this series states that steering angles above
MSA - 5 deg are seldom needed for maneuvering even at obstacle spacings
approaching the minimum required by the vehicles. Therefore, the MSA - 5
deg value is of interest since it appears to be a more practical value with

which to analyze vehicle force and its relation to soil strength.

90. The soil strength parameter that showed the best correlation with F_T/W was the 0- to 6-in. RCI. A plot of F_T/W at MSA - 5 deg for the lowest vehicle speed in each soil strength versus the 0- to 6-in. RCI is shown in plate 13. Curves of best visual fit were drawn through the data points for each vehicle. The F_T/W values were obtained from the curves developed in plates 11 and 12. Data used to prepare plate 13 are summarized below.

Item No.	O- to 6-in. RCI	F _T /W at MSA - 5 deg	Item No.	O- to 6-in. RCI	F _T /W at MSA - 5 deg
	XM410E1			MEXA 10x10 (Con	tinued)
194 198 202 206	194 29 44	0.12 0.12 0.17 0.07	246 250 254 256	24 210 19 14	0.14 0.06 0.06 0.08
	M35A2 (mod)	_		MEXA Tr	ack
210 214 218	46 34 198	0.14 0.20 0.07	274 278 282 286	52 32 24 154	0.21 0.23 0.25 0.21
238 242	MEXA 10x10 50 35	0.11 0.14	290 291 293	17 15 7	0.44 0.44 0.46

- 91. The curves in plate 13 show that for the XM410E1, M35A2 (mod), and MEXA 10x10 F_T/W increases only slightly between about 200 and 50 RCI. Below 50 RCI, F_T/W increases rapidly with little decrease in RCI. Two data points for the MEXA 10x10 (items 256 and 254) did not fit the general shape of the curves. No reason can be given for these apparent anomalies; however, erroneous torque data are suspected. The curve for the MEXA track indicates a slight increase in F_T/W between 160 and 30 RCI. Below 30 RCI, F_T/W increased rapidly with decrease in RCI. One noteworthy aspect of these plots is that the shape of the curves compares favorably with the curves developed in the towed motion resistance analysis.
 - 92. Plots were also made, but are not included herein, of $F_{\eta \gamma}/W$ at

MSA - 5 dcg versus the O- to 6-in. kCI at other vehicle test speeds. These plots revealed little change in the magnitude or shape of the curves presented in plate 13.

Minimum soil strength

- 93. In table 6, the 0- to 6-in. RCI's for items 272, 273, 293, and 294 show that the MEXA 8x8 and the MEXA track are capable of maneuvering on soil strengths equal to their respective experimental VCI_{lt}'s. For the other vehicles tested, the maneuver data are not sufficient to permit performance determinations based on soil strength alone. However, the results tabulated in paragraph 86 were considered once again, and the following statements can be made regarding these vehicles.
- 94. F_T/W is considered to be a relative measure of motion resistance. Keeping in mind that the VCI_{lt} of the MEXA track was established at 7, the data show that on RCI's of 7 and 6 the increased motion resistance from zero steering angle to maximum steering angle was not great enough to cause immobilization. Then since the XM410E1, M35A2 (mod), and MEXA 10x10 show a smaller increase in F_T/W with increasing steering angle than did the MEXA track, it follows that these vehicles also should be able to maneuver on soil strengths equal to their respective VCI_{lt}'s. As for the M13, additional test data are needed to determine the min f_T/W strength required for maneuvering; however, since the M13 f_T/W skid-steer vehicle, it is felt that it might require a soil strength slightly higher than VCI_{lt} for maneuvering.
- 95. The preceding analysis indicates that five of the six vehicles tested should be able to maneuver in soil strengths as low as their respective VCI_{lt}'s. Nevertheless, since motion resistance was shown to increase during a turn and increase in motion resistance reduces the maximum speed a vehicle can attain, it follows that maximum speed in a turn will be less than the maximum straight-line speed on a given soil strength. The following tabulation presents the maximum turn speeds and their related soil strengths. For comparison purposes, the tabulation also shows maximum straight-line speed for each soil strength (acquired from the speed-soil strength curves in plate 9).

	0- to 6-in.	Max	Speed, mph
Vehicle	RCI	Turn	Straight Line
XM410E1	24	10.3	12.0
M35A2 (mod)	34	6.5	8.0
M113	25	5.1	12.0
MEXA 10x10	12	5.2	5.5
MEXA 8x8	11	2.7	2.5
MEXA track	7	2.8	2.5

The tabulation above shows that in four of the six tests, straight-line speed was greater than turn speed. The results of two tests are considered anomalies because turn speed is greater than straight-line speed. Such anomalies are especially likely to occur in this kind of a comparison when the RCI value is near or at VCI_{lt} because the value of VCI_{lt} is usually slightly conservative. (Note that VCI_{lt} is 11 for the MEXA 8x8 and 7 for the MEXA track; see paragraph 73.) However, despite these anomalies, the data, in general, tend to support the hypothesis that the motion resistance encountered in a turn causes a decrease in the maximum speed of vehicles.

Performance of MEXA Vehicles' Articulated Steering and Inching Systems in Soft Soils

- 96. The three MEXA vehicles were equipped with articulated and "inching" systems. The articulated joint between each vehicle unit is, in the free position, capable of roll, pitch, and yaw. The inching system between each unit has the ability to move one unit of the vehicle while the others remain stationary. The maximum extension distance of each inching unit is 2 ft. (In fig. 27b, the inching cylinder between the two units of the MEXA track vehicle is shown in extended position.)
- 97. In seventeen of the VCI tests, after the vehicle became immobilized, the operator attempted to extricate the vehicle by means of articulating and/or inching. Vehicle performance in each test is described in the remarks column in table 2. The tests in which one or toth of the systems were used are indicated in the following tabulation and results are discussed in the following paragraphs.

		System Tested		
Vehicle	Item No.	Articulated	Inching	
MEXA 10x10	42	x	x	
	43	x	×	
	44	x	x	
	45	x	x	
	47	x	x	
	48	x		
	49	x	x	
	51	x		
	52	x		
MEXA 8x8	62		x	
	65	x	x	
MEXA track	77	x	x	
	79	x	x	
	80		x	
	81		x	
	84	x	x	
	85	x	x	
	_	_		
Tot	al 17	14	14	

Articulated steering

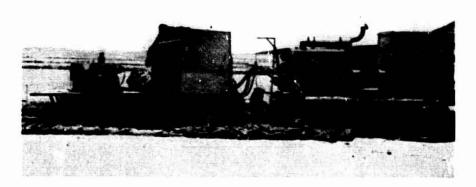
98. The roll, pitch, and yaw actions of the articulated joints of each MEXA vehicle were used in combination. Within limits, pitch and yaw actions can be controlled mechanically by the vehicle driver. With the articulated joint in free state, roll is induced by the terrain configuration over which the vehicle is traveling and cannot be controlled mechanically by the driver. Of the 14 attempts to extricate a vehicle by articulation, the MEXA 10x10 was the only vehicle that was able to extricate itself from an immobilization. The MEXA 10x10 attempted to become mobile through the use of the articulated steering in nine tests; attempts in four of the tests were successful. In item 48 the articulating action allowed the vehicle to extricate itself in a forward direction from the immobilization. In items 49, 51, and 52, text conditions were similar. In these three tests, the MEXA 10x10 was backed into the soft soil area until it became immobilized. The test vehicle first attempted to continue backing acress the soft soil using articulation but was not able to do so. The

vehicle then attempted to pull forward without articulating and could not. Articulation was again used and the MEXA 10x10 was able to gain enough traction to pull itself out in forward onto the firm ground that lay immediately in front of the vehicle.

99. Results of these tests indicate that articulation is of limited value as a means of extricating the MEXA vehicles from an immobilization caused by soft soil.

Inching system

100. The inching system (fig. 27) was designed so that, in theory, a vehicle could utilize inching to extricate itself from an immobilization in the following manner. With a vehicle composed of units A and B at the minimum length position (contracted), the operator can brake unit B and apply power to unit A and at the same time activate the inching cylinder located



a. Vehicle immobilized, inching cylinder partially extended

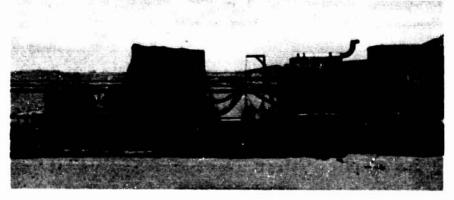


Fig. 27. MEXA track at Four Mile Flat site 8 (item 85)

between the two vehicle units. Thus, unit A can develop tractive effort and push against unit B with the inching cylinder. This would enable unit A to move to a new ground position. The functions of the two units are then reversed and unit B is drawn up to unit A. The vehicle could supposedly inch forward or backward to a position where the ground was firm enough to allow the vehicle to travel conventionally without inching.

- 101. The inching system was used on 14 immobilization tests. Fig. 27 shows the MEXA track during one test. The inching system was helpful in extricating the vehicle in only one test (item 62, with the MEXA 8x8). In 12 tests, either both units moved away from each other, although one unit's brakes were locked, or one unit remained stable whether it was supposed to or not, forcing the other unit to move to and from the first unit. The general observation made by test personnel was that once a MEXA vehicle became immobilized due to a soft soil condition, the more the inching system was used, the more deeply embedded the vehicle became.
- 102. These results indicate that for the MEXA vehicle, only in rare situations will the inching system contribute to a vehicle's efforts to extricate itself from an immobilization caused by soft soil.

Further Analyses

- 103. The analyses presented herein have been based on those aspects of the test data necessary to satisfy the purpose of the immediate program. The data collected during this program lend themselves to further analyses directed toward more detailed studies of acceleration, deceleration, and drive-line torque characteristics. This extension of data analyses would provide a basis on which to evaluate aspects of motion resistance, speed, and maneuver test procedures and vehicle response measurements and their ability to establish meaningful soil-vehicle relations. Additional analyses of these data are planned for the future.
- 104. The experience gained from the conduct of the tests and analyses of data in this program points up the need for updating and standardizing test procedures for conducting comprehensive soil-vehicle test programs.

Mechanical and Operational Problems of the MEXA Vehicles

Mechanical failures

- 105. During the course of the test program reported herein the following major mechanical failures occurred.
 - a. The MEXA 8x8 had five differential failures during the test program. These failures occurred in tests where the torque demand was at or near maximum torque output.
 - <u>b.</u> During a speed test on pavement the welds that held the MEXA 10x10 center drop box in place failed, allowing the center drive shaft to drop, causing extensive damage to both center drive shaft and drop box.
 - c. Numerous fatigue cracks developed in the vehicle frame of the MEXA 10x10 and MEXA 8x8.
 - d. On two occasions the main bearing of the power train at the back unit of the MEXA lOx10 failed.
 - e. The passive air springs of the MEXA 8x8 had to be relocated to prevent the spring support brackets from excessive deflections.
 - f. On two occasions high pressure hoses of the MEXA vehicles' hydraulic system ruptured.

Vehicle operation

106. The following deficiencies were noted during test operation of the MEXA vehicles.

- a. At times, especially at high speeds, the steering response of the MEXA vehicles was slow.
- <u>b</u>. Each time a MEXA vehicle was moved the vehicle's transmission and transfer case controls had to be adjusted to make gear shifting possible. The driver made this adjustment within 2 or 3 min by opening and closing a pressure release valve.
- c. The MEXA 8x8 was difficult to control in a tight turn. Because the front unit of the MEXA 8x8 was lighter than the second and third units, there was a tendency for the front unit to be pushed sideways. To correct this problem, the first-joint pitch control had to be used during a turn to transfer some weight from the second unit to the first.

PART IV: COMPARATIVE EVALUATION OF VEHICLE PERFORMANCE

pared on the basis of the results presented in Part III. These results include the experimentally determined VCI_{1t} and VCI₅₀, drawbar pull-speed relations, drawbar pull-soil strength relations, towed motion resistance-RCI relations, maximum speed-RCI relations, turning radius-speed relations, and force required in turning-soil strength relations. Except for the VCI₅₀ determinations, all performance correlations were made on the basis of one-pass performance. The similar relations developed for each vehicle are compared and discussed in the following paragraphs.

VCI Tests

108. Tests to determine the minimum soil strength that would permit the vehicles to complete one pass (VCI_{1t}) and 50 passes (VCI₅₀) in a straight-line path on level fine-grained soil revealed the following results:

	Experi	mental
Vehicle	vc1 ₅₀	VCI _{lt}
XM410E1	32	18
M35A2 (mod)	56	27
M113	29	15
MEXA 10x10	18	7
MEXA 8x8	23	11
MEXA track	21	7

109. The experimental VCI_{1t} and VCI₅₀ for the test vehicles showed that on the basis of "go-no go" for one pass and 50 passes in fine-grained soil, the three MEXA vehicles were superior in performance to the three military vehicles.

Drawbar Pull Tests

Drawbar pull-speed relations

110. The drawbar pull-speed curves for military and MEXA vehicles

are shown in plates 3 and 4, respectively. A comparison of performance in terms of drawbar pull divided by vehicle weight (D/W) versus speed shows that on soils strong enough for all vehicles to operate, the MEXA vehicles generally developed higher D/W values between 0 and about 2 mph. Beyond 2 mph the military vehicles developed higher D/W values. The data for these tests show 'hat the military vehicles could not develop enough force to produce 100 percent slip between their traction elements and pavement or the firmer soil strength. The MEXA vehicles in their lower gear apparently had ample power to produce 100 percent slip on all test surfaces.

Drawbar pull-soil strength relations

111. A summary of $(D/W)_{opt}$ versus soil strength curves for the six test vehicles is presented in plate 14. The curves show that the traction performances in terms of $(D/W)_{opt}$ for the MEXA vehicles are superior to those of the three military vehicles. From the minimum soil strength values, $(D/W)_{opt}$ for each of the military vehicles increased rapidly to about 50 RCI, beyond which little change occurred with increased soil strength. The $(D/W)_{opt}$ for each of the MEXA vehicles increased rapidly up to about 40 RCI. Beyond 40 RCI, the $(D/W)_{opt}$ for each of the MEXA vehicles increased little with increase in soil strength.

Towed Motion Resistance

112. Effects of soil strength on one-pass towed motion resistance for the test vehicles are shown in plate 15. Motion resistance divided by vehicle weight (R/W) is plotted versus 0- to 6-in. RCI. Performance curves in these plots indicate that for the soil strengths tested, R/W for the MEXA wheeled vehicles was less than R/W for the wheeled and tracked military vehicles. On soil strengths less than about 40 RCI, R/W for the MEXA track was generally less than R/W for the wheeled and tracked military vehicles. Above about 40 RCI the MEXA track's R/W was generally greater than that of the M113 and of the XM410E1 but less than that of the M35A1 (mod).

Speed Tests

113. Curves showing the effect of soil strength on maximum vehicle

speed on a level surface for the test vehicles are presented in plate 16. The plot shows one-pass maximum speed versus 0- to 6-in. RCI. A comparison of curves indicates that the performance of the MEXA vehicles as a group was superior to that of the military vehicles on soil strengths between 7 and 21 RCI. The M13 outperformed the MEXA track except in very soft soils below an RCI of about 20. The MEXA wheeled vehicles outperformed the M12 except on pavement. The XM410E1 outperformed all MEXA vehicles except in the very soft soils, below RCI's of 20-30. The M35A2 (mod) outperformed the MEXA wheeled vehicles in firm soils (RCI 70-80) and on pavement, and outperformed the MEXA track in soils firmer than RCI 40. On pavement the speed of the conventional military wheeled vehicles was about 2.5 times greater than the speed of the MEXA wheeled vehicles and the speed of the military tracked vehicle about 2 times greater than that of the MEXA track.

Maneuver Tests

Turning radius-speed relations

and soil strength on turning radius for the test vehicles is presented in plate 17. The plots show vehicle speed versus turning radius for each test vehicle on a range of soil strengths (indicated on the plots). As previously discussed (paragraph 88), for the range of soil strengths tested, soil strength appeared to have little effect on the vehicle's turning radius. A study of these relations indicates that at a given speed the military vehicles have smaller turning radii than the MEXA 10x10 and the MEXA track. The MEXA 8x8 turning radius was greater than that of the EMA10E1, about the same as the M35A2 (mod), and greater than the M113. Turning force-soil strength relations

115. The effects of soil strength on force required in a turn $(F_{\rm cy}/W)$ at MDA - 5 deg) for the XM410E1, M35A2 (mod), MEXA 10x10, and MEXA track are shown in plate 13. The performance of the MEXA 10x10 was about the same as that of the XM410E1 and was better than that of the M35A2 (mod). The performance of the MEXA track was the poorest of the four vehicles in this test.

PART V: SUMMARY OF TEST RESULTS, AND RECOMMENDATIONS

Summary of Test Results

- 116. Results of this investigation are summarized below.
 - a. VCI's established for the six test vehicles were:

	Experimental			
Vehiele_	vc1 ₅₀	VCI _{lt}		
XM410E1	32	18		
M35A2 (mod)	56	27		
M113	29	15		
MEXA 10x1.0	18	7		
MEXA 8x8	23	11		
MEXA track	21	7		

(See paragraphs 39 and 50 and plates 1 and 2.)

- <u>b</u>. The MEXA vehicles were superior to the military vehicles in terms of VCI_{1t} and VCI₅₀ (paragraphs 108 and 109).
- c. The best overall one-pass eritical-layer criteria determined from field tests for the six vehicles were: the 0-to 6-in. layer was considered to be the normal critical layer unless the RCI of the 6- to 12-in. layer was less than that of the 0- to 6-in. layer, in which case the 6- to 12-in. layer was eonsidered to be the critical layer (paragraph 42).
- d. The soil strength parameter that showed best overall eorrelation with drawbar pull, motion resistance, speed, and maneuver test results was the O- to 6-in. RCI (paragraph 51).
- c. On soil strong enough for all vehicles to operate, the MEXA vehicles generally developed higher maximum D/W values than did the military vehicles for speeds less than about 2 mph; at speeds greater than 2 mph the military vehicles developed the higher maximum D/W (paragraphs 54 and 110 and plates 3 and 4).
- f. MEXA vehicle performance in terms of $(D/W)_{opt}$ was superior to that of the military vehicles, thus indicating a greater traction efficiency. For the soil strengths tested, the military vehicles developed maximum $(D/W)_{opt}$ of between 0.50 and 0.60 and the MEXA vehicles developed maximum $(D/W)_{opt}$ of between 0.60 and 0.60 (paragraphs 57-64 and 111 and plate 5).
- g. Towed motion resistance (R/W) was less for the MEXA wheeled vehicles than that for the wheeled and tracked

military vehicles (paragraph 112). On soils of strengths below about 40 RCI the R/W of the MEXA track was lower than the R/W's of the military vehicles (paragraphs 65-69 and plate 6). Above about 40 RCI the R/W of the MEXA track was generally greater than the R/W's of the M113 and the XM410El but less than that of the M3:5A2 (mod).

- h. As soil strength increased from minimum values of VCI1t, vehicle speed increased, with the vehicles developing a maximum speed on pavement. The performance curves indicate that the speeds of the six test vehicles at their respective VCI1t's appear to be about 2.5 mph. Maximum speeds on pavement were: XM410E1, 53.0 mph; M35A2 (mod), 52.3 mph; M113, 30.2 mph; MEXA 10x10, 22.5 mph; MEXA 8x8, 22.9 mph; and MEXA track, 16.2 mph (paragraphs 76-81 and plate 9).
- i. MEXA vehicles do what they were designed to do--perform better on soft soils than military vehicles. However, on firm soil and on pavement, the three military vehicles performed better than the MEXA's (paragraph 113).
- j. For the range of soil strengths and speeds tested, speed appeared to be a more influential factor than soil strength in affecting the vehicles' ability to make a turn (paragraphs 84 and 114).
- k. The military vehicles had smaller turning radii than the MEXA 10x10 and MEXA track at the same speed for the range of soil strengths tested. The MEXA 8x8 turning radius was greater than that of the XM410E1, about the same as the M35A2 (mod), and greater than the M113. (Paragraph 114 and plate 17.)
- 1. Force (F_T/W) developed during vehicle turning action was slightly greater than straight-line F_T/W up to about 5 deg less than maximum steering angle. Beyond maximum steering angle minus 5 deg, force usually increased sharply (paragraph 86).
- m. The F_T/W required in a turn for the MEXA 10x10 was about the same as that for the XM410El and was less than that for the M35A2 (mod). The MEXA track required the highest F_T/W of the four vehicles tested (raragraph 115).
- n. The minimum soil strength required for maneuvering appears to be the same as VCI_{1t} for the XM41.0E1, M35A2 (mod). MEXA 8x8, MEXA 10x10, and MEXA track. Additional test data are needed to determine the minimum soil strength on which the M113 can maneuver. (See paragraphs 93 and 94.)
- o. The MEXA's articulated steering and inching systems contributed little to their abilities to extricate themselves from immobilizations caused by soft soil (paragraphs 96-102).

Recommendations

117. It is recommended that:

- a. Further analyses of the data be made. The analyses of data presented herein were limited to meet the stated objectives; however, additional test data were collected to permit comparative evaluation of test procedures and the development of other soil-vehicle relations that may lead to improved soil-vehicle relations or simpler testing procedures.
- $\underline{\mathbf{b}}$. The MEXA vehicles be repaired and reconditioned for use in other test programs.
- c. Additional tests be conducted in fine-grained soils to complete testing of vehicles on desired soil strengths that were not tested because of mechanical failures of vehicles. It is also recommended that tests be conducted on soils ranging in strength from 60 to 300+ RCI.
- d. Tests be conducted to refine testing procedures for determining maneuvering and slope climbing capabilities and effects of slippery surface on vehicle performance.
- e. Tests be conducted to determine the performance of MEXA vehicles on sands in desert environments.

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Table 1 Vehicle Data

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Table 2
Summary of Soil Data and VCI Test |

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														*1			1,	:-		elig get	~ ∪ 4, †	42		1),=1	0.7	χ.	40	47	110.3	69.3	54.
										••	••			.11	-+1	-q-f	411	••	::	-44	4.	• :			0.70		2			50.f	
	•							••						-					••			1.4	J. "}	· ·	0.24	.•,		92	71.2	ef . 3	٠4.
	5. *														•			••		+1	4.1	41	. 1	0. **	0.0	.*	• •	,2	?:.	29.ec	ж.

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Table 2
Surmary of Soil Dats and VCI Test Results

	ting C k of I	ayers		olsture			Dry 1	Density	(pcf)		Vane	Shear				Avg Rut	
0-6	1n. 6-12	12-18	(% Dry 0-1	0-6	6-12	12.18	of 0-6	Layers	1n. 12-18	c	¥°	Sv		tubbe **	Sr	Depth ln.	Remarks
		M1111	tary Vet	icles													
-Ton	XM410	El, 8x8	Truck,	Test W	eight 1	8,504 1	ъ										
33	36	55	11.0	53.5	67.0	52.0	€8.0	76.7	68.0	0.2	8	2.7	1.1	14	2.3	1.6 6.0 11.6	Vehicle dragged on mad buildup between ruts on 10th pass. H.d difficulty on 17th pass and extreme difficulty on 20th pass. Vehicle considered to be immobilized on 22d pass
32	40	50	+ 3.7	51.6	58.0	61.6	69.8	63.8	63.2	0.5	8	3.3	0.7	6	2.6	2.2 7.6 10.8	Vehicle dragged on mud buildup between ruts on 8th pass and became immobilized on 14th pass
56	62	62	60.8	61.9	42.6	45.9	60.5	73.5	68.7	3.6	50	10.4	2.2	14	6.5	0.1 1.8 2.3	Vehicle began dragging on mad buildup between ruts on 44th pass, but completed 50 passes with case
27	38	49	143.9	84.7	50.2	35.8	47.4	64.3	76.2	2.9	10	6.1	2.1	8	4.5	2.2 5.2 10.1	Vehicle began dragging an mud buildup between muts on 6th pass and had some difficulty making 39th pass. Vehicle completed 50 passes with difficulty
29	29	19	107.0	69.8				65.8	6.6	0.2	11	3.7	0.7	4	2.0	1.8 8.0	Vehicle began dragging on must buildup between ruts on 3d pass. There was some wheel allp on 5th pass. Vehicle became immobilized on 7th pass
•Ton				, Test h		-											
34	38	40	65.6	61.1		36.8			83.2	1.0	26	12.2	0.0	35	11.6	1.7 6.6	Vehicle began dragging on mud buildup between ruts on 45th pass, but had no difficulty completing 50 passes
17	20	30	95.5	76.8	66.6	37.9	51.2	58.5	80.7	4.3	20	10.3	0.9	25	8.6	3.8 11.8	Vehicle began dragging on mud build-up between ruts on 3d pass. By 5th pass vehicle was dragging entire test Jane. On 14th pass vehicle had extreme difficulty and was considered to be immobilized
10	17	21	135.5	84.7	61.5	46.3	48.6	62.5	70.9	2.7	ť	4.4	1.0	13	4.8	10.0	Vehicle entered test lane and became immobilized on 1st page
21	24	2 ^A	128.2	69.6	56.2	43.5	48.8	64.4	74.7	2.9	31	12.0	1.9	17	7.0	3.2	Vehicle began dragging on mud buildup by 10th pags, and was dragging entire test lane by 20t pags and having some difficulty. Differential caused mechanical difficulty on 35th pags, but vehicle openleted 14 pagses before test was stopped
3 l ı	3K	O4	19.9	26. 5	48.2	87.8	89.8	68.4	47.6	3.0	2ª	10.6	1.4	23	8.5	2.0 7.4 9.9 10.7	Undercarriage on left side was imaging on 7th pass. On 14th pass vehicle became immobilize in reverse gear due to lack of power to slip wheels. Vehicle traveled in forward gear through the lane and reentered test lane at opposite end. Fusses 14, 19, and 16 were completed in forward gear. Vehicle became immobilized on 17th pass in forward gear
21	55	16	21.4	28,1	35.8	60.9	86.4	79.9	12.0	3.54	24	11.4	0.4	28	9.8	9.1	Undercarriage begun dragging at start of 4th pass in reverse gear. Venicle continued throughout law, because immobilized near end of laws on 4th pass, and could not go forward
re	37	32	20.4	¥.3	€.1	€7.€	75.0	€0.0	*9.2	2.2	31	12.3	1.2	30	11.0	1.9 2.0 4.4	Vehicle completed (O passes with ease
in M	1542	mod/	fat Tru	ck, Test	Weight	111,20	10										
34	46	46	71.8	(4.5	44.7	4,0	€ C3 . I4	(i)	43.0	4.3	21	1 ^H •1	2.2	25	13.2	1.9	Vehicle began dragging on mud buildup by 7th pass and had some wheel slip on 34th pass. Vehicle had difficulty on 35th pass; difficulty increased until vehicle became immobilized of 41st pass.
48	*y#	6,5,0	€1.2	والمر والم	يا و بليا	48.4	19.0	73.0	44.4	4.0	• 4	21.0	0.2	ч.	19.6	2.0 11.8	Vehicle tegan tragging on mud buildup ty 12th pass and had some difficulty on with pass. Vehicle was able to complete 50 passes
31	ĻĻ,	50		59.4				72.								2.5 13.9	Vehicle began imaging in madicality by 9th pass and not difficulty on wist mass; sifficulty increased with each subsequent pass. Vehicle and extreme difficulty on 4'th pass at became freed life in 47th pass.
Z4.	30	47	110.3	19.3	54.8	41.1	4.9	6 2.4	70.0	2.1	27	1* •1	0.3	2	13.	14.0	Verifice tegon imaging slightly in stipss and was imaging entire lame by 6th pass. Verification the last in the pass in toward
14	2	11	115.6	90,é	12.6	45.3	44.0	€#.2	7*.1	4.4	20	11. ⁸	1.	;•	4.1	13.0	Vehicle proceded into test lane and tecame less tilliert a lat pass
21	3.	4!	75.2	65.3	14.0	34.0	€# ₄ 14	+7.6	~0.	4.7	21	15.2	0.4	34	14.0	:4.c	Vericle tegan tragging a rul builts; as at pair. By (to pair entire verticle undercarrings was dragging searly. Verticle and difficulty as Dt. pair and tennes law tilized on the pa
		22	0.3	o													Vehicle terane inn tillred a Di pada

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Table 2 (Continued)

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-	HPCA TO			4-4-	1		-	_			-				**		<u></u>		<u></u>	<u></u>	0-42	45-12	<u></u>	<u> </u>	36-10	<u>0-0</u>			Vehicle	
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,	site		- 1 2			,		.,											-	Je	.,0	J.J		0.76	0 07	-1				
34	Cars r Tire		4		1	: 64			117			40	18 72	54 66	55	70	t 3 70	::	:-	67 11 ¹	59 77	57 €7	0.67	0.64	0.49	45	38	50	18.7	36.8
					1,3	1 14		••			••	7.0		71 68	r B	74	H3 72	:-	::	138 129	6.9	73 70								
n.l									1 %					11	15	49	15	••	••	15	16.	55	0 -1	0.7-	•		1.0	n (*	**	~
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•	fars to Jose		5												1,12		1.0		••	79	10,7	120	1.12	0.48	0.60	89	59	72	16.9	51.2
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	u-	الإستان وال	Conten		Dans	ensity	(noe)			Shear	graph			Ave Post	
18	(% Dry	Wt) of		in.	of	Layers			Van	e S _v	R	ubbe ≰ ^o	S	Avg Rut Depth in,	Remarks
6	Vehicles							_	_		_	_	_		RCHAI AD
16 T	ruck, Te	st Wei	ght 18,	225 lb	(Cont	nued)									
The state of the s			57.6	81.2		65.3	52.4	3.0	25	17.8	1.0	29	16.4	2.8 4.3 5.6 8.4 9.8	Undercarriage was dragging on 19th pass. Vehicle was dragging entire lane by 24th pass. A large amount of mud had accumulated on tires and axles by 42d pass. Vehicle became immobilized on 46th pass
0	20. 8	27.4	46.0	73.4	91.7	71.6	54.2	4.0	27	18.2	0.5	30	16.5	5.3 12.1	Undercarriage was dragging on 2d pass. Vehicle had difficulty making 3d pass and became immobilized on $4 \mathrm{th}$ pass
	21.4	26.1	35.8	60.9	86.4	79.9	62.0	3.8	24	16.2	0.8	28	15.6		Vehicle became immobilized on 1st pass
8	18.7	36.8	64.7	85.0	82.3	60.2	48,6	4.5	26	18.1	9.7	34	19.0	3.1 5.2 7.4 9.6	Undercarriage was dragging on 23d pass. Vehicle became immobilized on 33d pass
В	20.1	36.7	65.3	66.6	76.2	59.€	58.2	3.5	28	18.3	1.8	30	17.8	2.6 4.1 6.0 8.0	Undercerriage was dragging on 23d pass. Vehicle became immobilized on 41st pass
	32.8	77.2	135.4	115.9	55.0	36.1	40.4	5,4	39	27.7	1.0	34	19.6	1.2	Undercarriage bugan dragging on soil buildup between ruts on 10th pass and was dragging entire test lame by 75th pass. Vehicle became immobilized on 31st pass
	16.9	51.2	103.1	108.3	67.1	40.6	42.7	2.8	42	27.A	0.4	38	21.8	1.2 5•3	Vehicle completed 50 passes with case
T	racked,	Test We	ight 2	,200 1	b										
	52.5	42.5	3€.2	36.2	77.2	84.3	85.1	3.R			0.6			::	Vehicle became immobilized on lat pass. Undercarriage was dragging
	34.€.	35.0	33.6	34.1	77.0	85.4	81.0	7.5	32	:2,4	0.8	33	€.0	1.9 9.4 13.8	Vehicle began dragging on 5th pass and was dragging entire test lane by 15th pass. Difficulty increased with each subsequent pass. Both tracks were slipping and vehicle became immobilized on 4th pass.
	44.2	37.1	32.4	3/4.1.	40.4	₽ .·	P4.2	, .5	l _k 4	13.5	0.0	.2	÷.0	1.4 21.5 11.9	Vehicle began drugging in 10th pass and was having difficulty in 12th pass. Vehicle was irragging entire lane by 16th pass and became irradialised in 25th pass.
	47.4	47.5	40.3	37.1	u.8	79.0	81. 8	17.2	20	20.0	1.2	31		3.7	Vehicle began dragging on 4th pass and was dragging entire lane by 7th pass. Both tracks were slipping and vehicle became ismobilized on 6th pass
	17.5	46.2	37.2	₩.0	ft.t	81.3	83.0	9.7	1.	11.4	0.4	33	4.5	3.2 14.6	Vehicle begon imagging in 4th pass and was dragging entire lane by 6th pass. It is traces were alipping and wehicle became immobilized in 7th pass
	*2.7	47.1	41.2	50.7	73.6	77.4	17.0	?•₹	21	. • c	0, 5	14	•?	18.4	Vehicle bigon imaging in it pass and was imaging entire lane by the pass. Vehicle had extreme distibulty in "the pass and became immedifiated in ith pass.
1	rackel,	Test W	-1ell: 3	2,000	1										
	74.€	** •	19.9	• 9.7	'	· i. • ·	7.4	7.4	24	fi, i	1.2	40	* . \$	2.7	Venicle was imagging slightly in 19th pass, but completed 50 passes with little difficulty
	40.7	(1,4	7. •	17.0	.7.0	1.71.1	811 . \$	* •*	. 144	··••	**.7	žŲ	•••	2.1	Vehicle was imagely slightly of the pass and by life pass was dragging entire test lane, difficulty in reased with each subsequent pass and ampass 10 vehicle terame insuffice.
	·4.0	• , f ,	•7.7	·1.·	€.2 , 3	15,2	(la , la	4.	14	F.1	live	şâ,	4.9	<u> 7,</u> 4	Vehicle regan draphing aligntly on bit pass or and tuilding and to hit pass vehicle was dragging entire inne. Vehicle was having a me difficulty after but pass, I hitle taid difficulty studies to rate at several places along lane and became insubilized but was able to extribate likely under our power. Vehicle was run on soil nearby that was of higher strength to remove was and reentered lane for "Phi pass but could not stay in rule and technic immobilized. Tender examines to be transitized on goth pass."
	.4.19		4,2,4	. 2		* J * *	··.ē		. 44	• '	all I	, bx	ξ,,	1	University to the traping a -th pass, let I has extreme this only on the pass and become first bound to pass in reverse
	•		51.a	13.	∾ •	***		ş		•	1.1	٠	\$. M		Discretization of an imaging is full pass and was imaging of the last type of pass. Well be tall extreme shift they as were pass and to see the strifted a core pass.

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	Fur Mile Fint		Yes	1	0	,	14.		11	22	•-	19 19	17 24	21 28	21 31	2tl 34	37	::	::	19 13	19 24	23 31	0.56	0.72	0.59	11	14	14	44.1	40.5	
	Four Mile Flat	140	Yes	1	1	11) •	14	14	18	14	1ć	21	23	27	27	31	••	•	15	20	2.	0.56	0.66	0.64	8	13	17	44.0	52.2	
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Table 2 (Continued)

ng Cone		oisture	Cort		Descri	Deneity	(inca)			Sheat	grapt	1			
f Layers	(% Dry	Wt) of	Layers	, in.	of	Layers	in.	_	Van			lubbe	S	Avg Rut Depth	
2 12-18		0-6		15-10	0-6	0-12	12-18	<u> </u>	Σ	_	-	ř	<u></u>	in.	Remarks
itary Ve				10											
racked,						· -	1								
22	17.9	26.5	41.4	62.1	05.4	67.5	51.4	2.9	20	6.7	1.3	a	4.0	2.h 5.0 2 11.6	Undercarriage began dragging on 14th pass and was dragging entire lame by 16th pass. Vehicle had difficulty backing up on 38th pass and became immobilized on 44th pass in reverse, but traveled forward out of text lame and received lame at opposite end in forward gear. Vehicle became immobilised on 49th pass in forward, and considered to be immobilised on 44th pass.
30	20.4	36.3	66.1	67.6	75.0	60.0	59.2	2.2	31	6.5	1.2	30	5•3	1.7	Vehicle completed 50 passes with ease
14	44.1	40.5	52.0			68.5		1.9		2.3	1.2	6	1.9	11.0	Vehicle became immobilized on lot pass. It appeared that had the end been of slightly higher strength, wehicle might have teen able to complete 1 pass.
17	44.0	52.2	49.4	46.8	67.9	68.2	70.5	2.5	3	2.9	1.8	5	2.5	9.0	Vehicle became immobilized on 1st pass. Vehicle's maximum speed just before immobilisation occurred was 2.88 mph
М	EXA Vehic	les	_												
, 10x10	Truck,	Test Wei	ght 18	.030 1b											
. 4	84.8	62.8	51.4	50.1	61.5	70.5	71.0	••	••	••	•-		••	::	Vehicle immediately become immobilized on lat pass. Undercarriage was not dragging. Yehicle's yaw, pitch, and inching actions ware tried, but vehicle could not extricate itself
8	31.5	44.3	49.9	49.1	74.6	70.2	66.0	4. 8	20	6.0	0.0	34	2.2	3.3 6.6 7.2	Undercorrings began dragging on 24th pass. Vehicle hed extreme difficulty completing 29th pass and became are bilized on 30th pass. Vehicle's yaw, pitch, and incning actions were tried, but vehicle could not extricate itself
11	44.7	44.2	46.3	i.l2	76.8	74.9	76.0	14 .14	31	6,4	0.1	30	5.0	0.3	Vehicle's difficulty increased with each subsequent pess. Undercarriage was dragging entire test lane on 3'th pass. Vehicle became immobilized on both pass. Vehicle's yaw, pitch, and suching actions were tried, but vehicle could not extricete itself
5	62.9	52.8	43.8	42.3	69.4	77.2	78.5	1.6	16	2.5	0.5	10	1.0	2.6	Vehicle became immobilized on 2d pass in forward grar. Undercarriage was not dragging. Vehicle's yaw, pitch, and inching actions were tried, but vehicle could not cetricate itself.
9	48.1	37.6	35.6	37.2	85*1	85.5	93.6	2.7	1	2.8	0.6	8	1.0	1.4	Vehicle began dragging on 5th pass and was dragging entire lame on 10th pass. Wheel slip oc- curred on line pass. Vehicle had difficulty on 14th pase and actrame difficulty (high slip on 26th pass, but was able to complete 29th pass at 0.14 mph. Vehicle considered to be im- mobilised on 25th pass.
9					Use	e test	ll date							1.4	Vehicle began dragging on 4th pare, had some difficulty completing 13th pass, and had extreme difficulty (high clip) on 16th pass. It became immobilized on 20th pass. Vehicle's yew, pitch, and inching actions were tried, but vehicle could not extricate itself. Vehicle considered to be immobilized on 16th pass
18	55.5	49.9	46.3	49.0	70.7	77.9	71. ⁸	6.5	13	7.2	0.5	2€	2.3	0.8 12.1	Gradual rutting occurred with each pass until undercarriage was dragging entire lake on 20th pass. Vehicle had extreme difficulty (high slip) after 39th pass. A large emount of mud had accumulated on tha tires by 39th pass. Tect was halted after 47th pass to cool torque converter. Vehicle managed to complete 56th pass at 0.15 mph. Forward progress completely stopped on 57th pass. Yaw and pitch actions were tried, and after about 10 min wentleds was able to axtricate itreal from test lane. Vehicle concidered to be immobilized on 47th pass
15	222.3	144.9	77.9	67.3	32.7	53.0	58,7	••	••	••	9.0	l _a	0,5	5.0	Vahicle repeated procedure of that of test 44, and was considered to be immobilised on 1st page
22	72.6	57.5	55.7	43.7	ii.,	€€.8	₩.o	••	••	••	1.0	9	1.5	1.1	Area covered with about 2 in, of soft slush atop soil of much higher strength. Vehicle easily completed 50 passes
21	112.7	89.0	€1.9	1.2.1	48.0	e3.0	77.9	••	••	••	0.6	8	1.1	5.5	Vehicls backed into soft area until it became immobilised but was able to extricate itself in forward using pitch and yaw action. Vehicle considered to be immobilised on lst pass
17	299.3	144,9	77.9	67.3	32.7	*3.0	. 8.7	••	••	••	0.4	Ļ	1,1	÷.0	Vehicle was backed into soft area to allow ratrieval with winch (on front of vehicle). Vehicle became immobilized but was able to extricate itself in forward using pitch and yew action of hydrealic system. This procedure was repeated three these and each time vehicle was able t entricate itself in forward. Vehicle considered to be impobilized on lst pass.
22	18.3	23.8	47.4	n8.1	42,4	70,4	47.7	2.5	27	ř.3	1.2	<u>.</u> s.	4.2	0.1 1.4 2.5 3.4	Yenicle completed "O pasons with maps
19	19.5	34.5	37.8	•# . 9	92.1	79.4	€3,	j3	jai N	€.4	0.;	2.4	1.2	1.2	Must began to accumulate on tires on 124 pass, and a large amount has accumulated by dist pass Undercarriage was dragging on 564 pass, but venicle completed to passes
13	. 5.1	51,6	4.7	12.1	(5,4	ee.3	17.2	1.4		2,3	1.2	9	2.2		Vehicle entered test lane and as tires became covered with and, it allowed from and soon te- came imposilised (on first pass). Undercarriage aid not areg
											5.9				Venicle entered test lane and as tirre torane revered with most, venicle showed down and more

(Cetterel)

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B

Table C (Continued)

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 				 _			_	_													1-12	115110	0-1)			ic'es (15.
																				•	2) /2-Tor	Mary			, Test			1).
F 457 PC 02									17	1		16.0					10	1/	24,	0.54		0.13						53.4	
Although the Charles								! !	ė.	I.	, *j	5.					11	21 24 16	.14. .14.			O.f.G						53.h	
r 1 = 1.* •1• 1									1-	3		40	**	41, 1, c	::	::	1'	20	26) (1	0.1	0.71	C.70	8	15	?0	50 . °	51.1	51.2	50
																						2-	1/2•T	or. M20	A. '5x 4	True F.	Test. We	lebt 1 i	.01
								••										4.7		0.04	0.44	0.11						22.9	
					: :					× ,		5.1		. ""		174	11	25 17	50										
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electrical de la constante de						,	••	::		**	и,			. 1		1	10	.74		C•· l.	0.40	0.111	19	12	12	1.2	1.1.4	₹9 . /	37
4					· · · · · · · · · · · · · · · · · · ·				17	:			•				.*>	1 4	. '	^•r*	C.rh	0.53	19	11	13	• 3,9	49.8	30.1	T.F
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Table 2 (Continued)

	ing Co		M	alsture	Centen	+	Dry I	ensity	(pcf)			Shear				Ave Put	
	in.	12-18		Wt) of	layers (•12	, in.	of I	eyers.	ir.	c	Van ≱°	Sv	B	ubber ≱°	Sr	lepti.	bemarks
			icles (Continu	ed)												
MEXA	10x10	0 Truck	, Test	/eight	18,030	1b (Con	tinued	<u>)</u>									
5	11	17	47.1	-1.0	13.4	41. 8	70.5	(6.3	(5.0	1.5	16	5.4	1.0	Q,	1.6	6.6	Vehicle became immobilized on 1st parc. All tires were slipping at immobilization and com- pletely sovered with mod. Undercarriage did not imag
(11	17	47.1	·1.0	52.4	51.8	70,5	4	(5.9	1.	14	4.4	3.0	15	1.0	7.1	Vehicle bream fractilized in 1st pass, fill tires were slipping at innellifaction and were completely covered with out. Undercarriage did not arms
8	14	50	50.5	51.1	11.2	·0.2	68.0	69.8	ec.h	2.4	1	3.0	2.2	1,	2.9	£ .(Vehicle terand immedilization, hit pass when all times became covered with mud and began slipping
/2-T	n MFX/	A, HxB	Truck,	Test We	ight 1)	,013 1h	•										
43	29	22	44.6	37.0	37.9	34.9	81.6	ŖĻ. ∙B	84.0	5.0	30	Ω	0.1	÷l,	l. • †	0.4	Undercarriage began dranging on 8th pass and was dragged entire test lane on 16th pass. Vehicle had difficulty on 31st pass, and extreme difficulty (high sitp) after 40th pass, but was able to complete 50 passer. Maximum speed on 50th pass was 0.95 mph
24	50	20	37.2	35.8	પ્ય. પ	₹4.5	83.5	84.1	7h •h	∃•5	19	7.4	1.0	2.	3.7	0.1 G.4 11.0	Vehicle began tragging on 6th pass and was dragging entire lane on 16th pass. It had extreme difficulty (high slip) on 3-th pass. All eight sheels were slipping on 5th pass, and wennishe was making very little forward progress. It was considered to be immobilized on 3th pass.
20	13	15	53.9	41.2	35.8	3€ •0	76 .f.	A3.	₽Ş•(3.5	12	4.7	n.F	9	1.E	1.0	Venicle was drawging on 4th pass with some wheel slip and was drawging entire test lane on 6th pass. Vehicle had extreme difficulty on 6th pass and was able to complete loth pass at only did one. On lift pass all wheels were spinning and vehicle was making very little forward propress and was considered to be immobilized. Vehicle's inching action was used, and after 15 cla of effort vehicle was able to extricate itself.
19	12	12	51.2	1110	19.1	37.5	78.7	² 0.	A.	1.0	11	4.2	()•1	۲,	3.1	1.4	/ small amount of surface water was on larg after lat pass. On jd pass vehicle startel slipping all eight wheels and to ome immedilized. Underpartings was not drugging. Vehicle was able to book out of test lane.
c.	15	13	53.9	k≒ . ş	36.4	₹;•0	70.4	80.4	92.7	1.0	1 12	7.4	3.4	ţA	\$ • \$	1.1 3.2 10.7	Vehicle began to drag on 6th pass and was dragging entire test lane on 2th pass. Vehicle's aifficulty increased dim each pass. Spend on JOCH pass as 0.41 eph. Vehicle considered to be immedilized on dist pass as all wheels were slipping and very little forward progress on being made.
A	13	12	4,5 _e t,	والمرابا	1.1.1.	40.2	¢7.4	15.4	40.)		j =	E / . [3	••"	?	 •	0.7	Vehicle's undercarriage was iragging on 7th pass and was dragging entire lame on 17th pass. Vehicle had extreme difficulty (high slip) on .3t pass, and speed on .3th pass was only 0.5th eps. Vehicle considered to be irredicted on 2 to pass. Yaw, pitch, and inching actions were tried, but has vehicle condition textricate itself.
43	11	21	1,4,0	41 fs	ď.	14.0	H1.4	47.4	H., (*	7.1	41,	11.0	0.4	iş r	4.7	О. Н	Vehicle towar to image 1 the page. While "O pages with relative case
34	14	11	žį i 📲	4 .3	e7 .t.	ξ° •ι	ਮੌੜ੍ਹਾ	મુટુ હ	~1.0	1.3	41,	10.7	1.1	43	4.	0.r 9	Vehicle was granging on 7th pass and was tranging entire test lane on litt, pass. Vehicle's difficulty gratually increased with each subsequent pass. Spection ofth pass was 0.55 mpm. Wheels were slipping on Foth pass with very little forward progress. It was considered to be involving on Foth pass.
(P)	14	17	19.4	(4.• *	\$7. H	1.4 _e u	92.1	7-14E	€ 2.1	2	žĸ	7.	ť°•	747	••	1	Must tegan to a complete on tires of 1999 pass. Vehicle experies of extreme inff only, and undercarriage was drugging a tire west line by 224 pass. Vehicle started forward and the No. 2 differential railed
٠	н	14	1.1	ŧ,	L.,-	u "t	1.0	2,0	fr •=2	2	12	<u>.</u>	1.	4	1.0	1	Well be extered but line to tight speed test. Notice on a list line where it is of the line will be a second on the line with all times slipping. Taken arrive was a triangley
ĵů	10	14	44.1	40.	•	L-12	-, 2	€"•"	1.	1.	1	•	T C		.*•		Vettore tenses are adding a lar pass were all time to the exercise of and topo- adding the Debuggerings was not imaging
20	11	1.5	41.6	•	., · .	L	-1.+	. •	•	•		• •	ţ •'		4.1		If there is set in worse, who twist end by but pass, with a tilizent, a course of the pass, and time were aligned to dust energing tile to trag.
	1 = -	24	ų,t	1 . 1		4	•••	:	3				ı.				Network for a like fluident or satisface. These wire inated with hids, indepluye age it is a little of
1			52.7	• • • •	1.	1.	x 1 • 2			-		* •*		t	•	7,	to 400 to see the attitude of the page. Their series, this is tray at any other
	5 Y : -	1,	inst b.	er t	156 11												
r							•••	245	- •				•			 B1	Setum to a more tiers of cet gaze 4 of those total uses. It consider was tracefore
	30	1	1 ₂ 1 • 15	, ° , -	m* • •	41.41	2.			2.0		٠.		**	**	r .**	Tennel's franz at the ups cartes each end space, and end considerate fraction picture is part to sale of a solution fraction fra solute, we did to be easier to set the solution of the solution of the sale and the solution of the sale and the solutions of the sale and the solutions of the sale and the solutions of the sale and the solutions of the sale and the sale an
ود		:	, t _r .	49,7	ا ۽ اب	₩.		•	4.	••	••	••	••	••	••	Ċ	P.D.E. Stillage was Many Levellon labels. It para to the first the selection of a viting gain

Table 2 (Concluded

		-	2.1		Path						7-	n. [law e4	Tropp #1	e tr						Cone I			lding	Index					oisture Wt) of	
ter u-	1. 19*1 7	1.31	<u> </u>	1933	155		-	4	<u>.</u>	Ξ.		nt in	G G	12	s, in	12	2.,	30	ď	0-1)		12-18	0-6		12-18	0-6	in. 6-12	12-18	0-1	0-6	į
																												MEXA Ve	hicles	(Continu	1€
																										MEXA	Track	Test	Weight	19,680 1	<u>.t</u>
77	WEC		Virg	_*	i	11		::	13			11	10	10	12 12	15 18	34			14	10 8	12 13	0.49.	0.55	0.58	7	6	7	68.6	58.4	
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70		14	Yes	24	:	12	::				 	1 1	14 20 12	12	6,2 -4 -5.1	81 30 22	1,1, 1 ^t 11		 	46 31	45 30 14	43 32 20	0.63	0.52	0.36	2 9	24	15	4€. 4	40.1	
90		1	Yes	.12	0 1 15,	74			10	::	::	-4 5' 13	વર્ષ સં. 16	21	40 -0 -3	.2	31 30 31	::	::	(1 57 13	41 33 18	29 30 28	0.40	0.44	0.42	2h	19	12	35.8	33.9	
91	į.	11	Yes	11.		* 1	::	::	12	::	::	7h + 0 12	71	20 12 13	42	41 31 27	33 32	::	::	/2 5,8 11	64 67 16	42 50 24	0.34	0.42	0.47	24	27	20	38.9	33.8	
^R 2	Carson Hink site 3	ł _i ł _i	Ilos		1	7k,		::	.20	0		2 8 22 8 2	144 1-0 217 218 2	30 30 32	2% 48 48 48 21	13 to 14 to 15 to	14.	::	:: :: ::	hr 19 5; 17 39	43 48 36 31 28	32 39 34 39 35	0.77	0.78	0.59	35	34	19	19.0	28.3	
93	Carson Sins site 3	t _a s.	4.	••		1			1 1 2 1 0 1		26	20 21 1) 22 20 10	27 27 24 22 22	27 21 28 21 24	20 27 30	30 31 31 31 31 31	41 42 42 42 42 43 41	::	::	31 40 24 24 20 18	27 30 24 25 23 22	30 32 28 29 31 26	0.74	0.72	0.65	23	19	20	21.4	28.1	
94	Four Mile Flat site 7	13	Yes	,	2		1.1	14	11	14	1*	14	17	14	25	51,	10			13	17	23	0.46	0.58	0.63	6	10	14	58.8	48.4	
A5	Four Mile Flat site "	1.47	Y. s	£3) 	/			.,	10 1±	17	17 14	20	전. 전	, Vi	::	::	4	13 16	20 21	0.38	0.57	0.62	3	7	15	54.2	50.3	
*	Four Mile Flat	13 ^H	tin	••	n 10	7 .		٧,	214	40	15	31	27 17	27	7321	40	- 14			10	28 21	28	0.61	0.74	0.71	16	21	20	19.2	43.8	ı

Table 2 (Concluded)

g Cone Laye n. 12 12	(%	Dry W	t) of 0-6				Density Layers, 6-12		<u>c</u>	Vane		graph h	ubber	s _r	Avg Rut Depth in.	PMRSIKE
ck, 7	est Weig	nt 19	680 1	b (Cont	inued)											
6	7 68	3.6	58.4	44.6	42.1	65.0	76.4	78.1	1.0	16	2.2	1.8	A	1.8	7.5	Vehicle became immobilized on 2d pass: undercorriage was dragging. Vehicle's yaw, pitch, and inching actions were tried, but the vehicle could not extricate itself
8	8 50	7.7	44.7	40.9	38.4	76.1	79.0	83.4	4.8	1	4.8	1.7	10	2.3	4.8 31.9	Vehicle began dragging on 2d pass and was dragging entire lane on 3d pass. It became immobilized on 5th pass
3 1	15 46	.u	40.1	33.2	33.1	80.2	87.2	84.8	3.7	1	3.8	1.2	8	1.5	1.7 12.6	Vehicle began dragging on 7th pass and was dragging entire lane by 10th pass. It had difficulty completing 20th pass and became immobilized on afth pass. Vehicle's yaw, pitch, and inching actions were tried, but the vehicle could not extricate itself
B 1	12 35	8.6	33.9	34.7	34.6	86.0	85.9	84.1	9.0	2	A.1	0.0	42	2.4	1.2	Vehicle began dragging on 8th pass and had extreme difficulty (high slip) from 16th pass to 22d pass in which immobilization occurred. Vehicle's inching action was tried, but the vehicle could not extricate itself
	20 38	3.9	33. 8 ·	35.5	35.0	84.h	84.2	83.2	5.4	0	5.4	0.3	39	2.4	1.4 10.3	Vehicle began dragging on 12th pass, had some difficulty on 10th pass, had extreme d'fficulty on 13t pass, and became immobilized in 18th pass. Inching action was tried, but the vehicle could not extricate itself
. 1	19 19	•.0	28.3	46.8	76.2	78.3	67.2	52.4	2.7	28	4.2	1.0	20	2.4	1.7 2.9 6.6 7.0	Undercarriage was dragging on mud buildup between ruts on 35th pass. Venicle completed 50 passes without difficulty
4 2	റെ 21	.4	28.1	35.8	60.9	86.4	79•9	62.0	3.8	بالح	5.0	0.0	28	2.2	1.6 4.9 7.7 10.4	Undercarriage was dragging on mud buildup between ruts on 15th pass. Vehicle completed 5- passes with some difficulty thrack slip;
1	4 58	8.8	48.4	55•3	51.8	73.2	67.4	68.2	1.6	6	1.8	1.2	Q	1.9	19.0	Undercarriage began dragging heavily on "th pass. Vehicle became immobilized on the pass. Vehicle's yaw, pitch, and inching actions were tried, but the vehicle could not extricate itself
1	.2 54	••5	50.3	60.7	57.1	71.1	63.9	66.2	1.0	Q	1.4	1.0	7	1.3	10,8	Vehicle became immovilized on Pd pass going forward. Vehicle's yaw, pinch, and inching actions were tried, but the vehicle could not extricate itself
4	90 49	.2	43.8	42.7	44.2	74.0	73.2	73.0	5.2	45	2.4	1.6	7	1.0	12.	Vehicle was dragging entire test lane by Itt pass. Hifficulty in travel increased with each pass after 13th pass. Vehicle completed "O passes with difficulty

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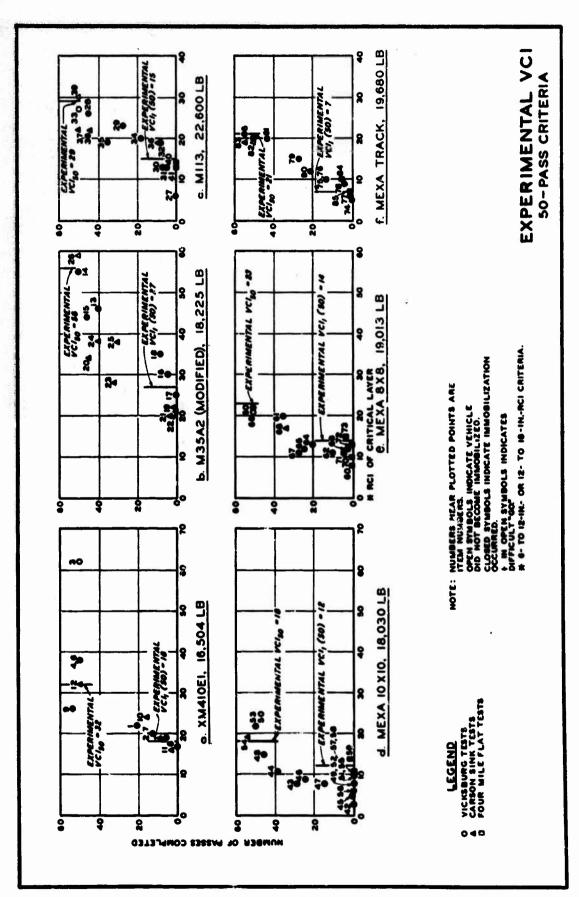
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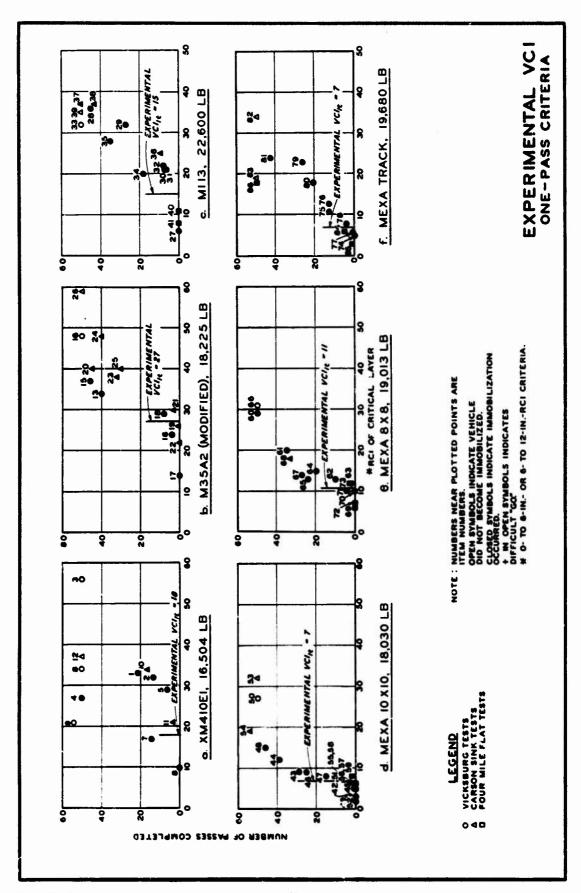
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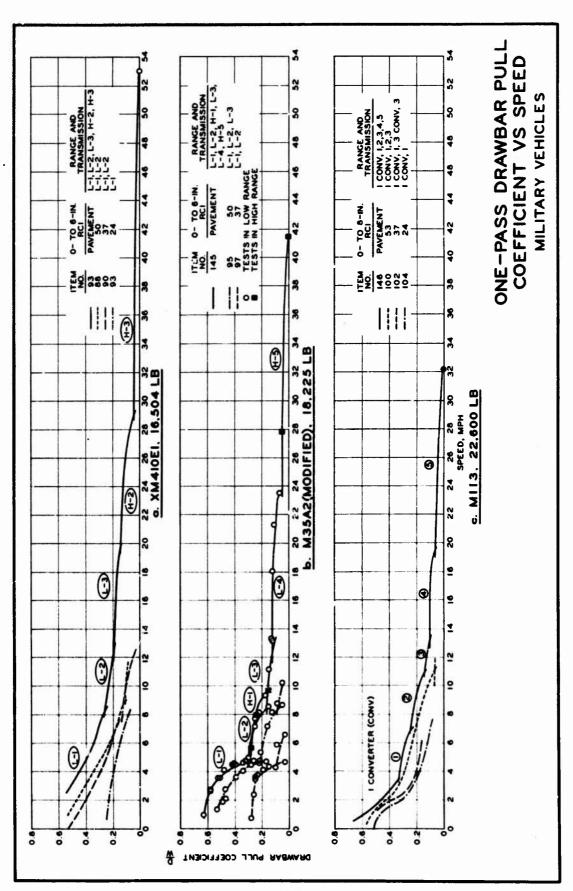
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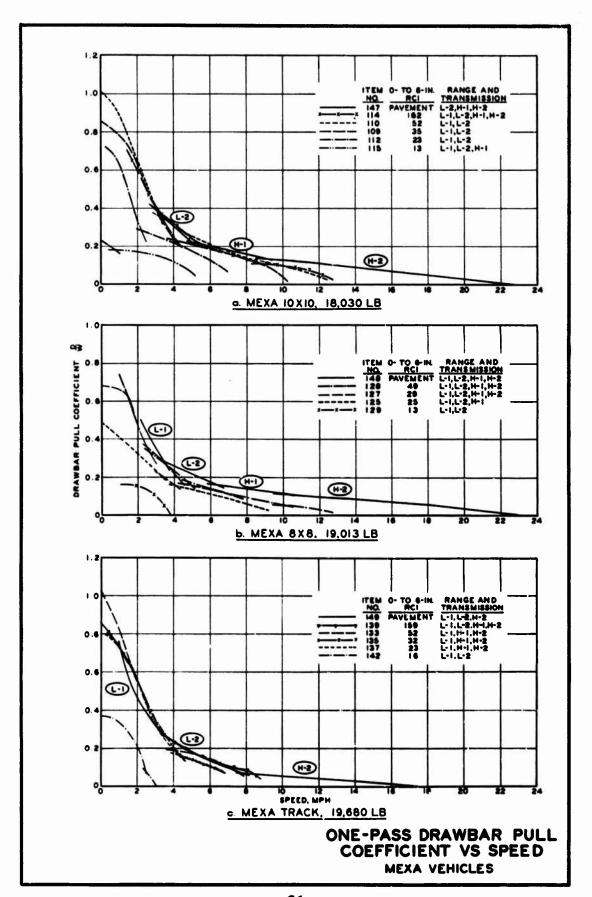
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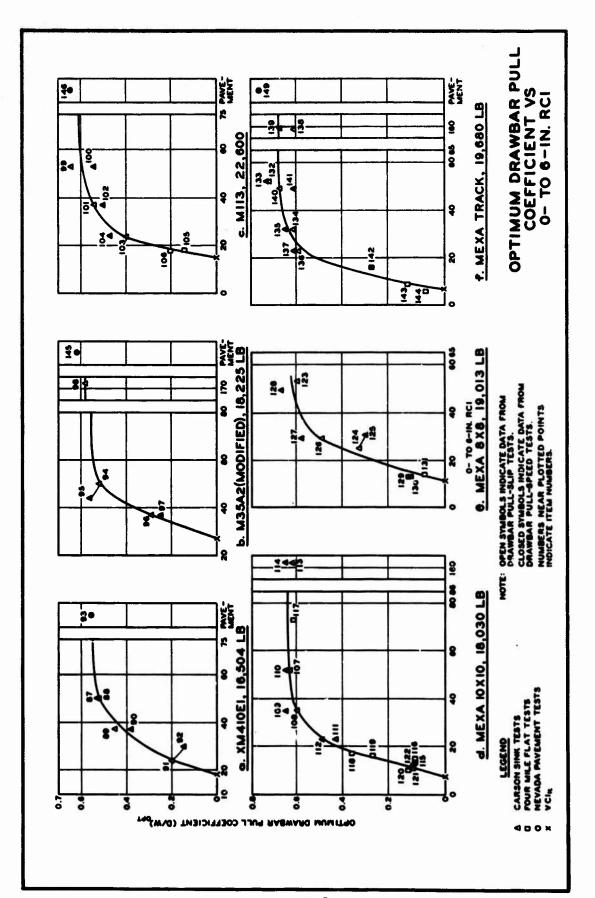
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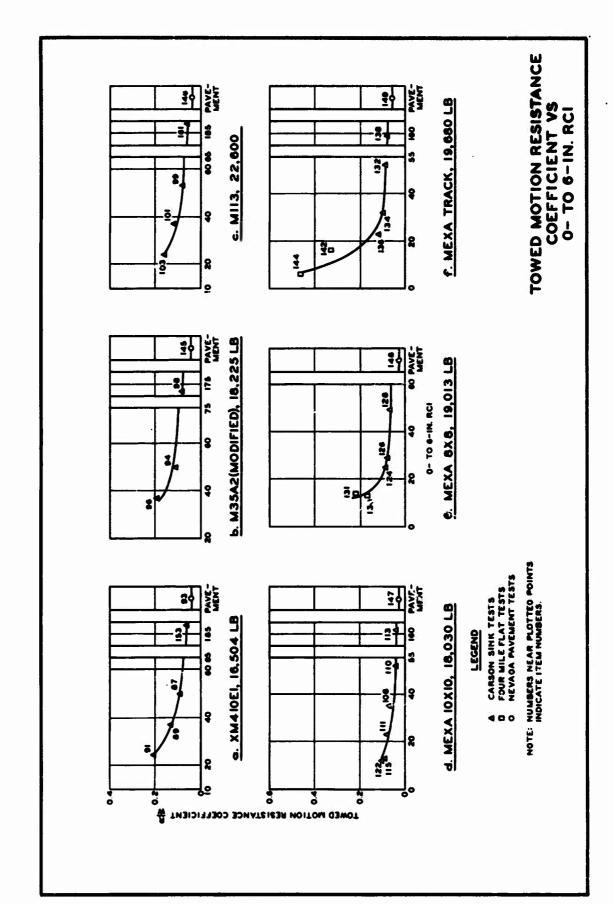


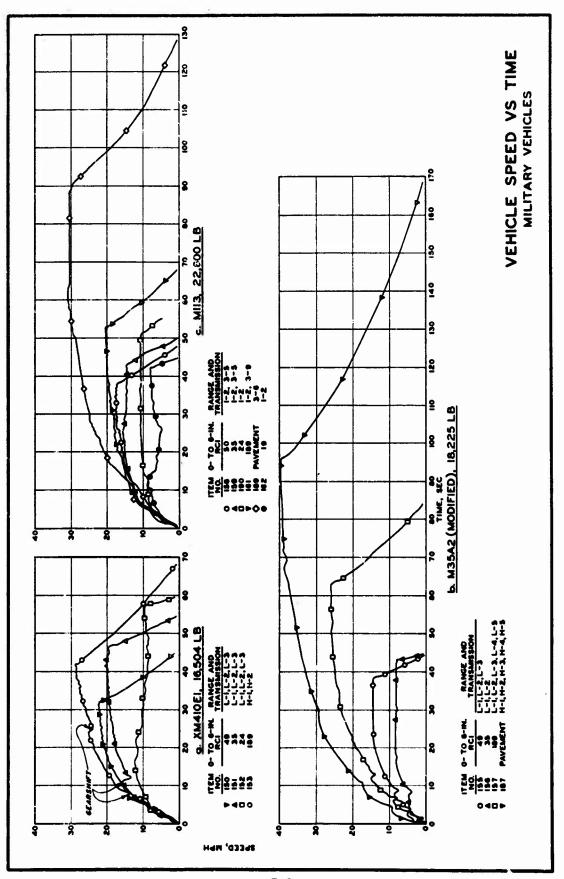


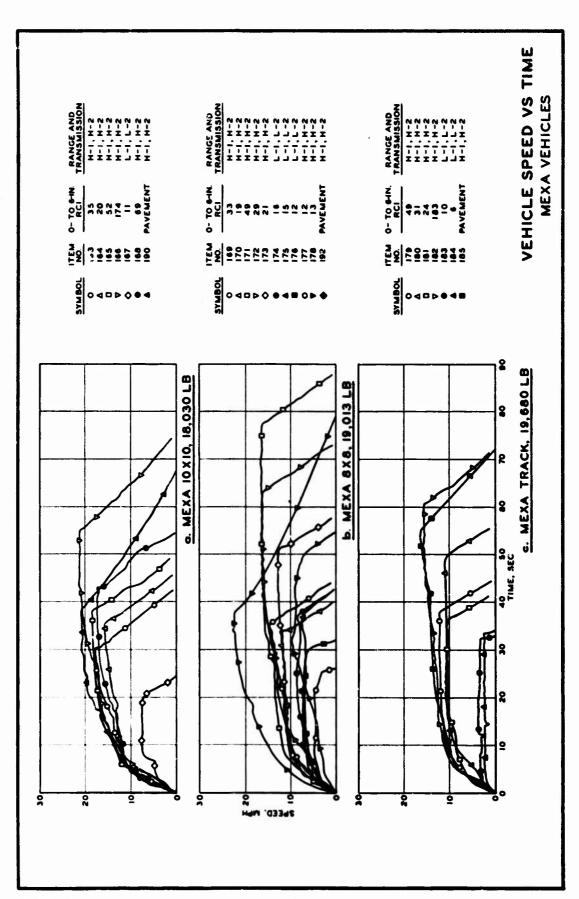


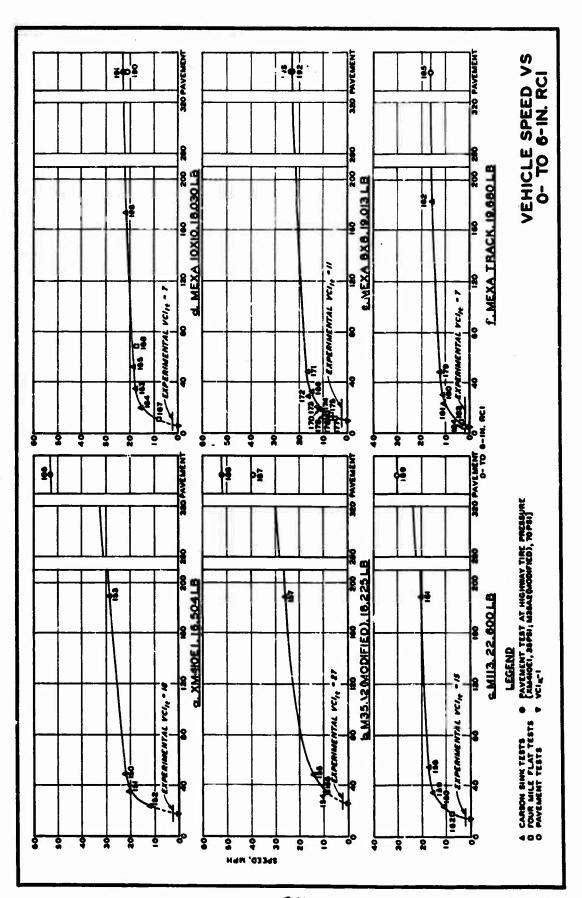


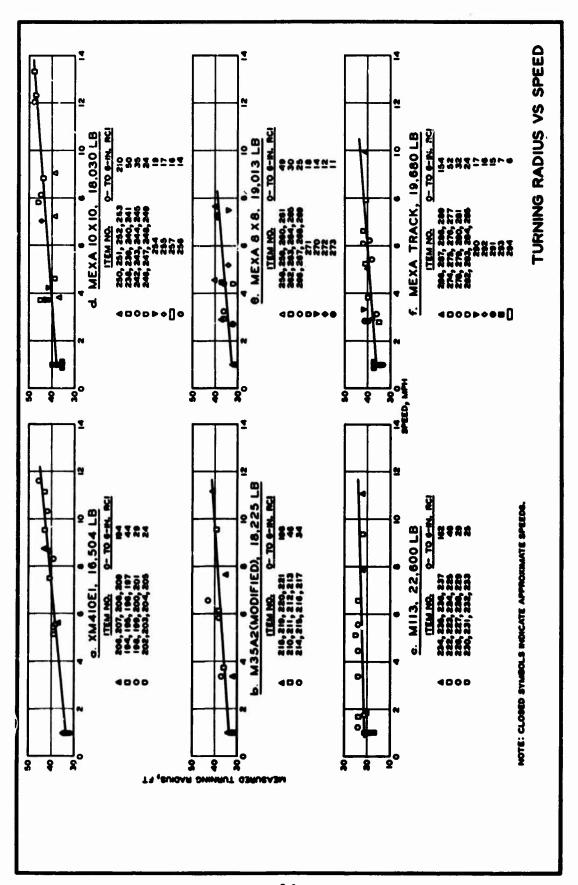


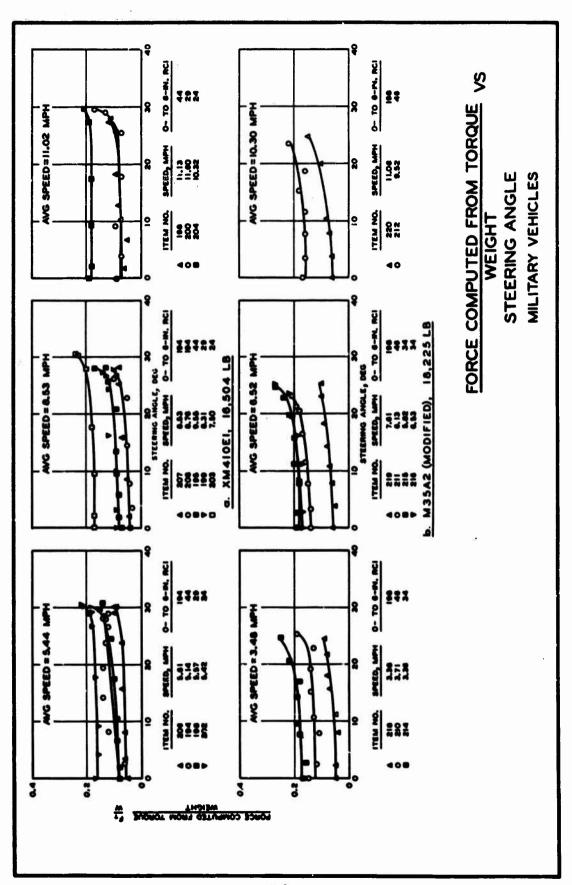


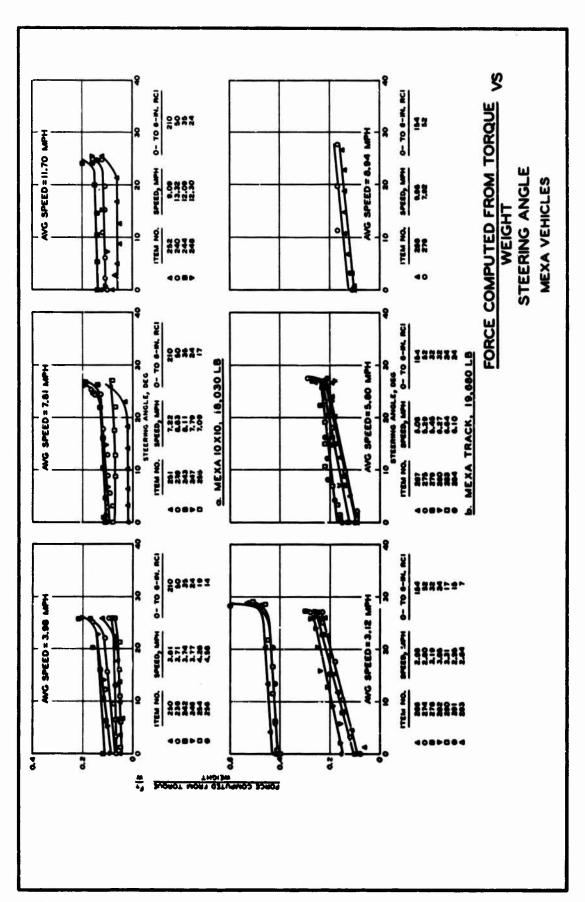


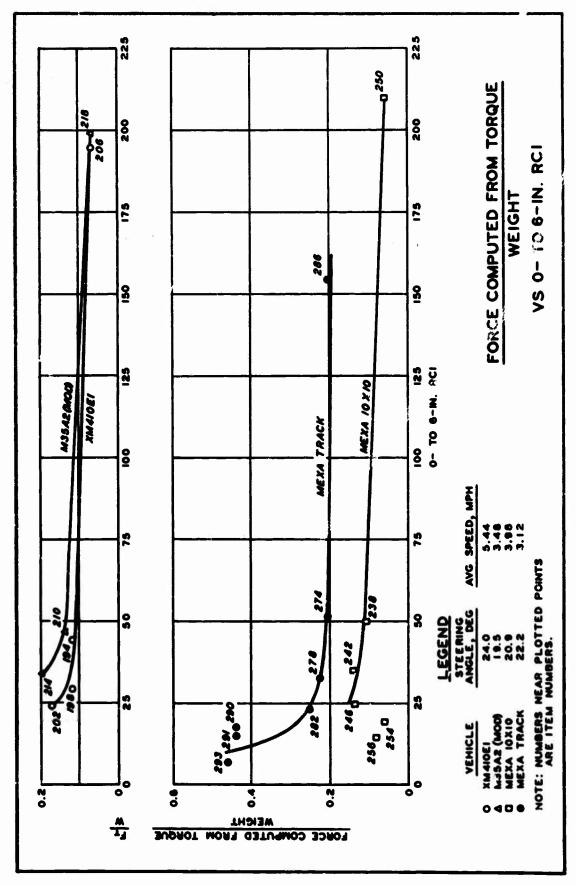




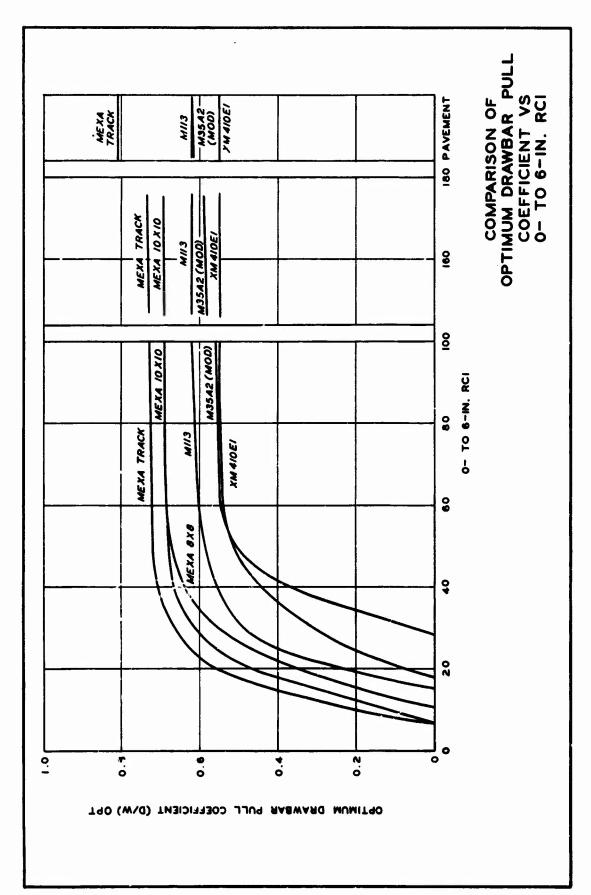


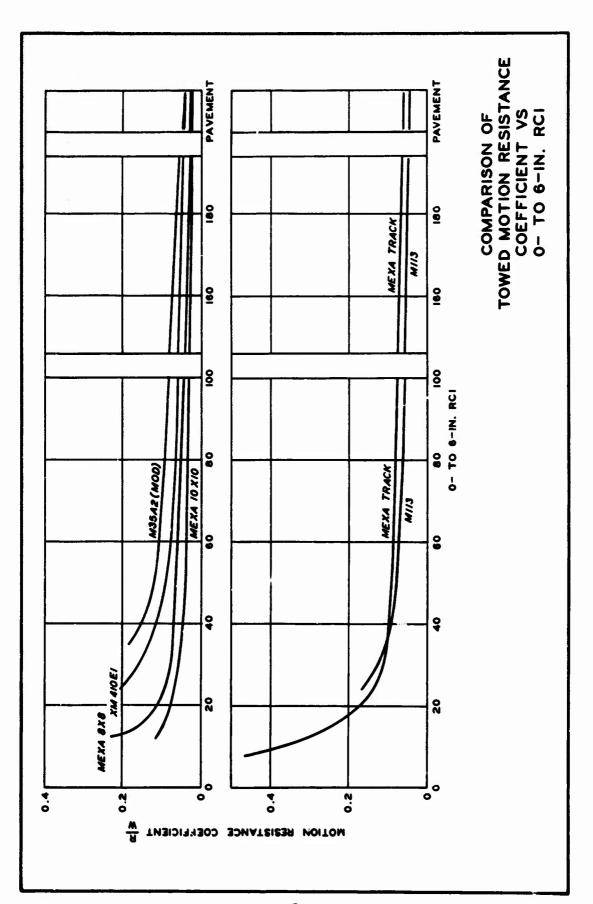


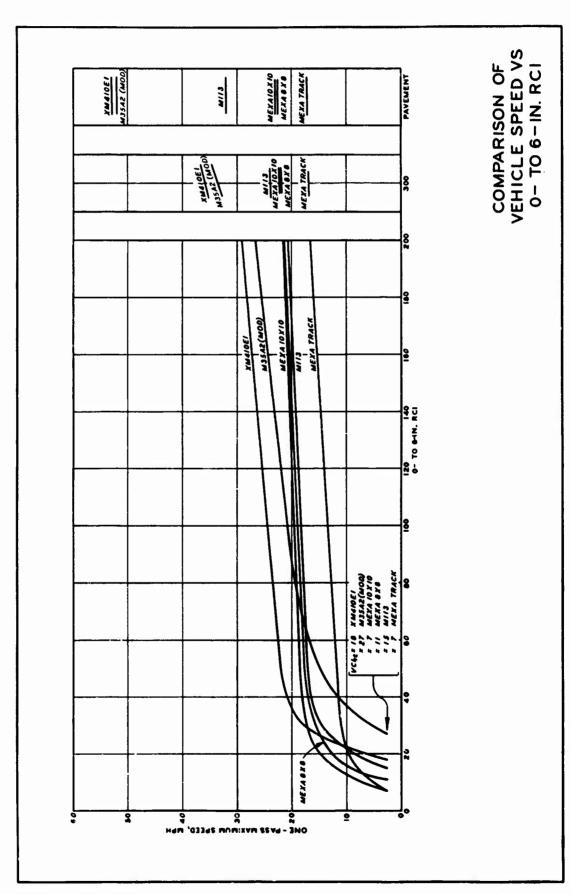


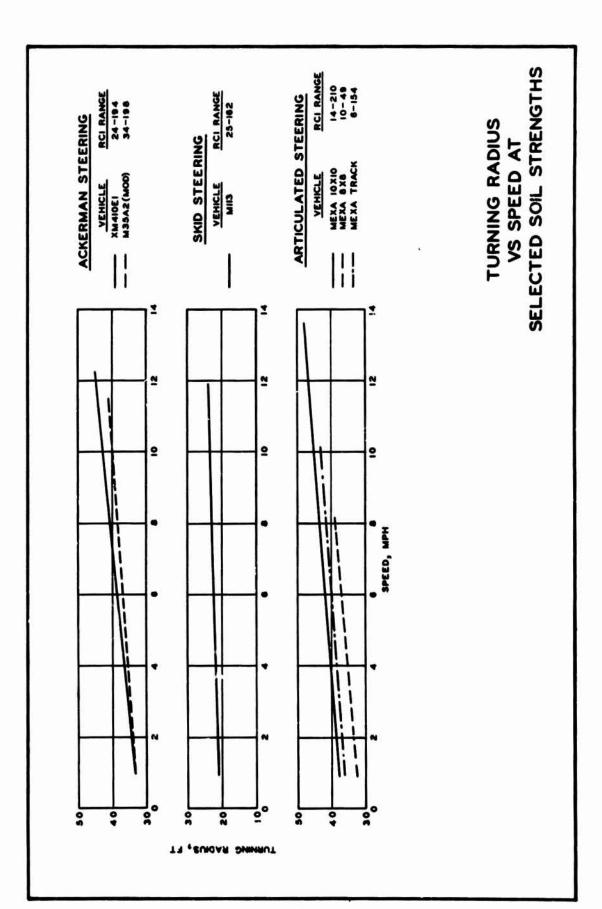


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In the concept phase of Mobility Exercise A (MEXA) the principal purpose was to design vehicles capable of operating in remote areas of the world where extremely soft soils				
predominate, and to develop a program of tests for evaluating these vehicles in soft				
soils. As a result of the MEXA concept phase, two 2-1/2-ton wheeled and one 2-1/2-ton				
tracked vehicles were designed. The designs of the vehicle characteristics were in				
part derived from three existing systems that provide for predicting vehicle perform-				
ance relative to soil strength. These syst	ance relative to soil strength. These systems were the U. S. Army Engineer Waterways			
Experiment Station (WES) soil trafficability system, the WES mobility numeric system,				
and the Land Locomotion Laboratory soil value system. After the MEXA vehicles were				
fabricated, a field test program was designed and conducted. A total of 328 tests				
were conducted on level clay soils, at two sites near Vicksburg, Miss., and at eight				
sites near Fallon, Nev. The purpose of the test program was to evaluate the performance of the three MEXA vehicles (MEXA 10x10, MEXA 8x8, and MEXA track) and three mili-				
tary vehicles (XM410E1, M35A2 (mod), and M113) on a range of soil strengths. Further				
purposes of this study were to compare the performances of the three MEXA vehicles with				

those of the three military vehicles and to compare the measured and the predicted performances of the vehicles, using the three prediction systems from which the MEXA vehicles were designed. The measured and predicted performance comparisons are presented in Appendixes A, B, and C, Volume II. Test results indicate that the MEXA vehicles do what they were designed to do, i.e. perform better on soft soils than military

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Security Classification LINK C LINK A LINK . **KEY WORDS** ROLE WT Military vehicles Mobility Mobility Exercise A Soft soils Soil strength Trafficability Vehicle performance

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